

Mixed Integer Programming Approaches for Experimental Design

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Joint work with Denis Saure

DRO brown bag lunch seminars, Columbia Business School
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Motivation: (Custom) Product Recommendations



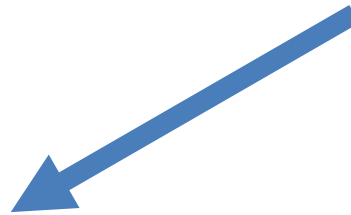
Feature	SX530	RX100
Zoom	50x	3.6x
Prize	\$249.99	\$399.99
Weight	15.68 ounces	7.5 ounces
Prefer	<input checked="" type="checkbox"/>	<input type="checkbox"/>



Feature	TG-4	G9
Waterproof	Yes	No
Prize	\$249.99	\$399.99
Weight	7.36 lb	7.5 lb
Prefer	<input type="checkbox"/>	<input checked="" type="checkbox"/>



Feature	TG-4	Galaxy 2
Waterproof	Yes	No
Prize	\$249.99	\$399.99
Viewfinder	Electronic	Optical
Prefer	<input checked="" type="checkbox"/>	<input type="checkbox"/>



We recommend:



Motivation: (Custom) Product Recommendations



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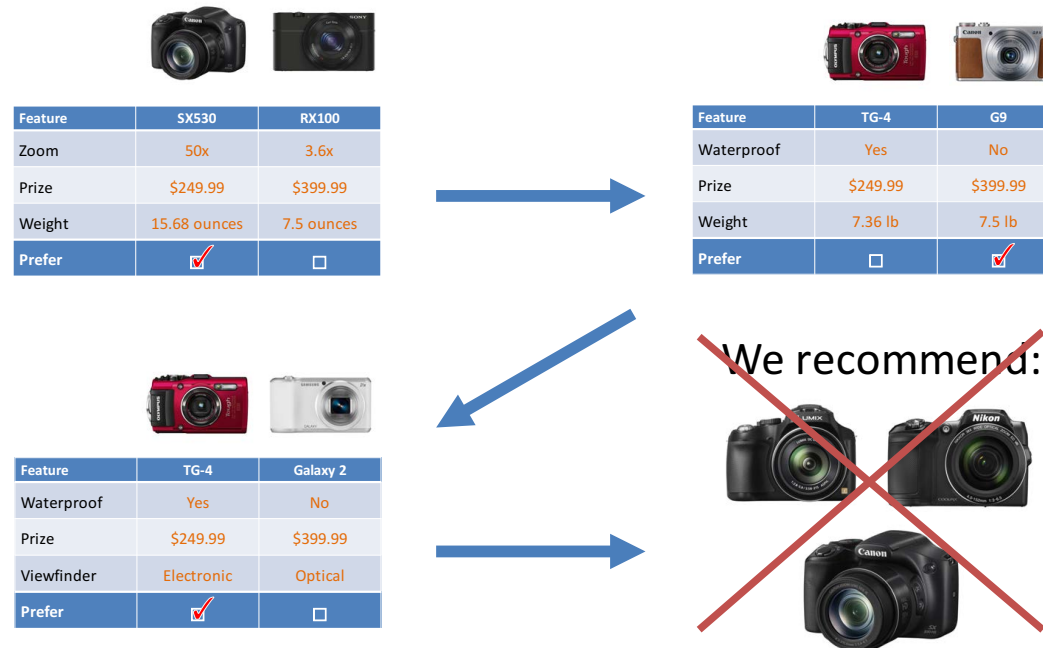
- Toubia, Hauser and Dahan (2003)
- Toubia, Hauser, and Simester (2004)

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“Towards” Optimal Product Recommendation

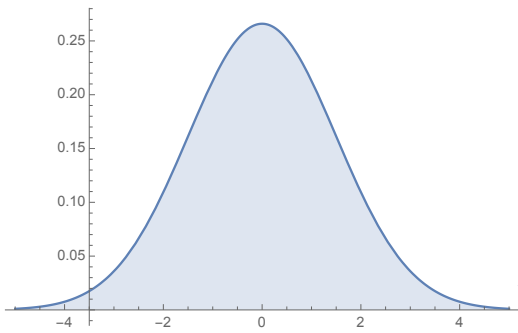
- Find enough information about preferences to recommend



- How do I pick the **next (1st) question** to obtain the largest reduction of uncertainty or “variance” on preferences
- Compensatory model estimation (**part-worths**), not just assortment

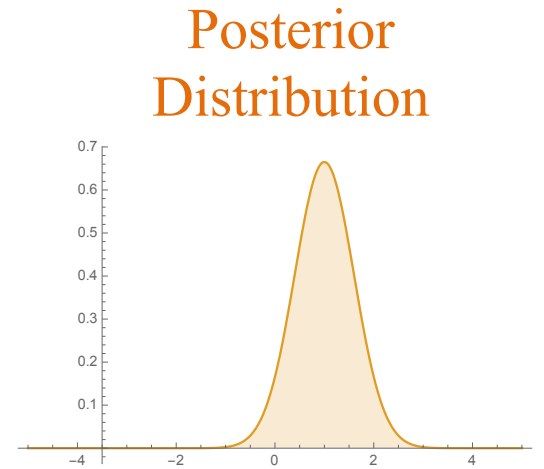
Next Question To Reduce “Variance”: Bayesian

Prior Distribution
of β




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Bayesian
Update
→

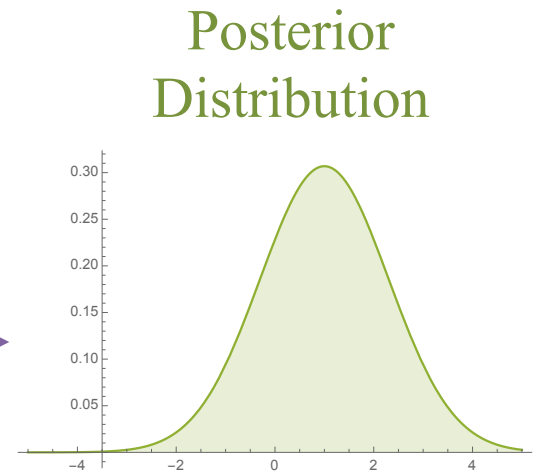


MCMC



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Prefer	<input checked="" type="checkbox"/>	<input type="checkbox"/>

Bayesian
Update
→



- Black-box objective: Question Selection = Enumeration 😞
- Question selection by Mixed Integer Programming (MIP)

Traveling Salesman Problem (TSP): Visit Cities Fast

Firefox File Edit View History Bookmarks Tools Window Help

Google Maps

http://maps.google.com/

Gmail Google Notebook La Tercera Apple Insider Currency Converter

Web

How scientists can avert a NEW FLINT CRISIS

The urgent need for DROUGHT-PROOF ENERGY

Exploring the landscape of COSMIC HABITATS

AMERICAN Scientist

May-June 2016 www.americanscientist.org

Cyber-Insecurity

The latest digital threats call for a smarter, stronger response.

SIGMA XI THE SCIENTIFIC RESEARCH SOCIETY

Paradoxes, Contradictions, and the Limits of Science

Many research results define boundaries of what cannot be known, predicted, or described. Classifying these limitations shows us the structure of science and reason.

Noson S. Yanofsky

“A computer would have to check all these possible routes to find the shortest one.”

MIP = Avoid Enumeration

- Number of tours for 49 cities = $48!/2 \approx 10^{60}$
- Fastest supercomputer $\approx 10^{17}$ flops
- Assuming one floating point operation per tour:
> 10^{35} years $\approx 10^{25}$ times the age of the universe!
- How long does it take on an iphone?
 - Less than a second!
 - 4 iterations of **cutting plane** method!
 - Dantzig, Fulkerson and Johnson 1954 did it by hand!
 - For more info see tutorial in ConcordeTSP app
 - **Cutting planes** are the key for effectively solving (even NP-hard) MIP problems in practice.

50+ Years of MIP = Significant Solver Speedups

- Algorithmic Improvements (Machine Independent):
 - **CPLEX** v1.2 (1991) – v11 (2007): 29,000x speedup
 - Gurobi v1 (2009) – v6.5 (2015): 48.7x speedup
 - Commercial, but free for academic use
- (Reasonably) effective free / open source solvers:
 - GLPK, **COIN-OR (CBC)** and SCIP (only for non-commercial)
- Easy to use, fast and versatile modeling languages
 - Julia based JuMP modelling language
- Linear MIP solvers very mature and effective:
 - Convex nonlinear MIP getting there (even MI-SDP!), quadratic nearly there

Choice-based Conjoint Analysis (CBCA)



Feature	Chewbacca	BB-8
Wookiee	Yes	No
Droid	No	Yes
Blaster	Yes	No
I would buy toy	<input checked="" type="checkbox"/>	<input type="checkbox"/>

$$\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = x^2$$

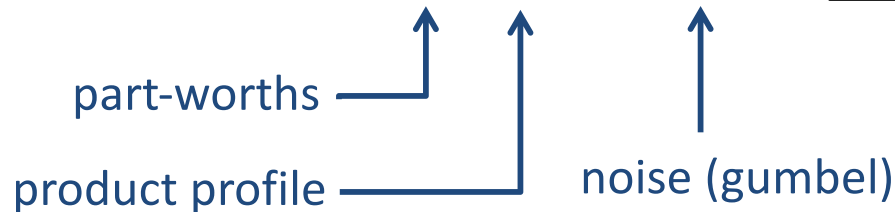
Product Profile x^1 x^2

MNL Preference Model

- Utilities for 2 products, n features (e.g. n = 12)

$$U_1 = \beta \cdot x^1 + \epsilon_1 = \sum_{i=1}^n \beta_i x_i^1 + \epsilon_1$$

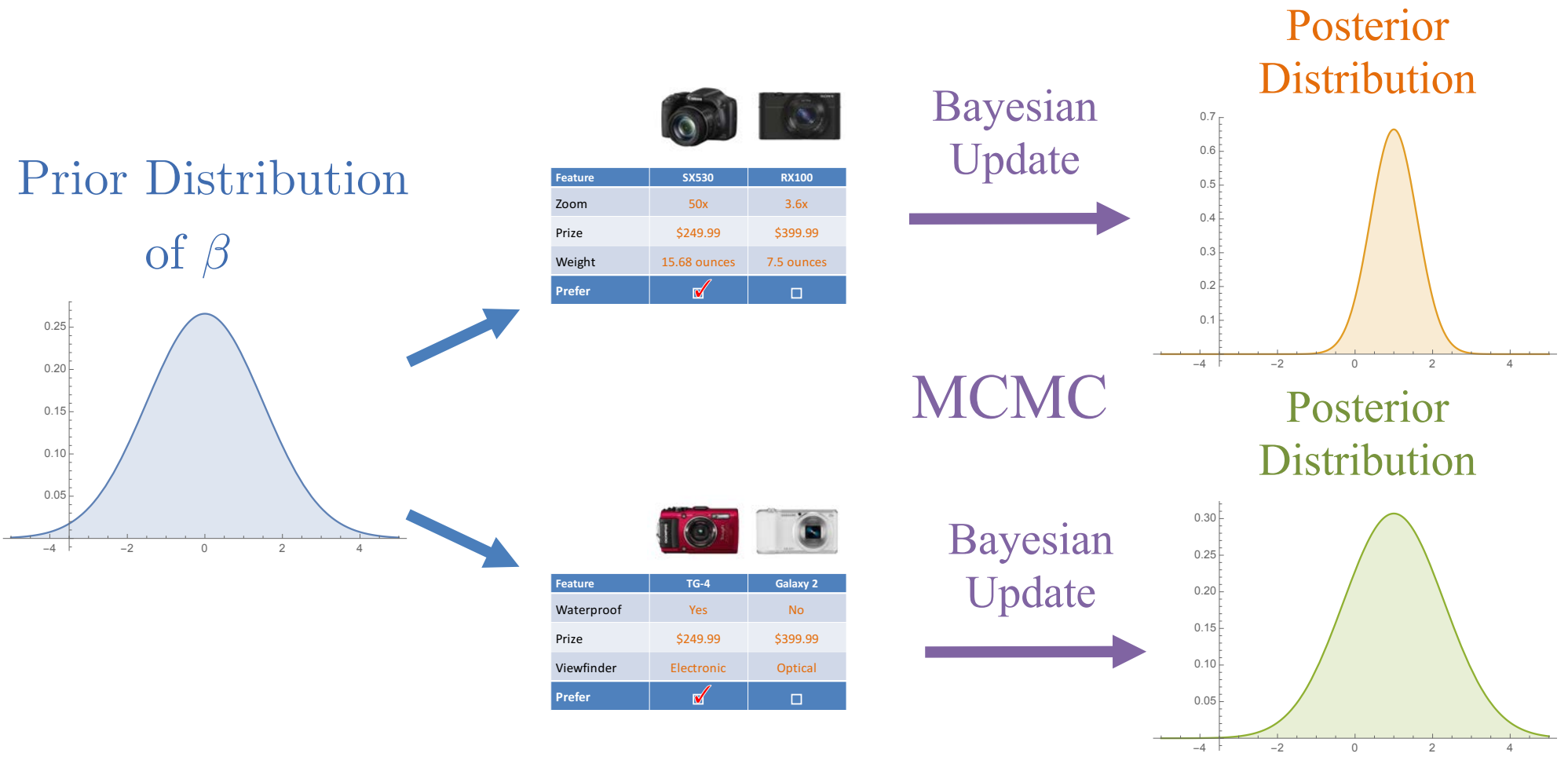
$$U_2 = \beta \cdot x^2 + \epsilon_2 = \sum_{i=1}^n \beta_i x_i^2 + \epsilon_2$$



- Utility maximizing customer: $x^1 \succeq x^2 \Leftrightarrow U_1 \underset{\text{red}}{\geq} U_2$
- Noise can result in response error:

$$L(\beta | x^1 \succeq x^2) = \mathbb{P}(x^1 \succeq x^2 | \beta) = \frac{e^{\beta \cdot x^1}}{e^{\beta \cdot x^1} + e^{\beta \cdot x^2}}$$

Next Question To Reduce “Variance”: Bayesian



MNL Preference Model



Logistic Regression

$$\beta \cdot x^1 \geq \beta \cdot x^2$$



$$\beta \cdot z \geq 0 \quad z = x^1 - x^2$$

“Linear” Experimental Design



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Unknown $\beta \in \mathbb{R}^n$



$$\{\beta \cdot z^i\}_{i=1}^q$$



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Prize	\$249.99	\$399.99
Viewfinder	Electron	Optical
Prefer	<input checked="" type="checkbox"/>	<input type="checkbox"/>

Questions:

$$Z = [z^1 | \dots | z^q]^T \in \mathbb{R}^{q \times n}$$

Answers:

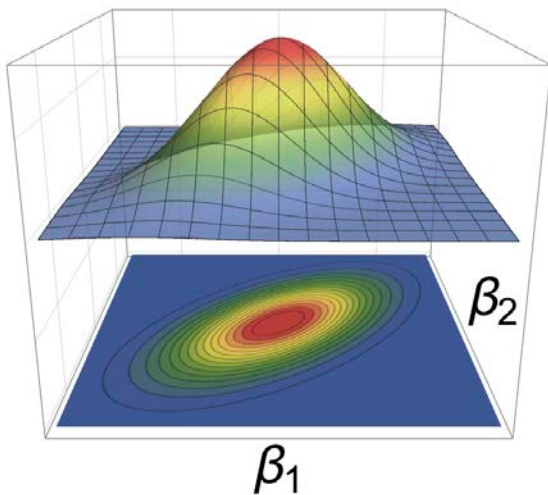
$$Y = [y_1 | \dots | y_q]^T$$

$$\text{Model: } \mathbb{P}(Y | \beta, Z) = L(Y | \beta, Z) = \prod_{i=1}^q h(y^i, \beta \cdot z^i)$$

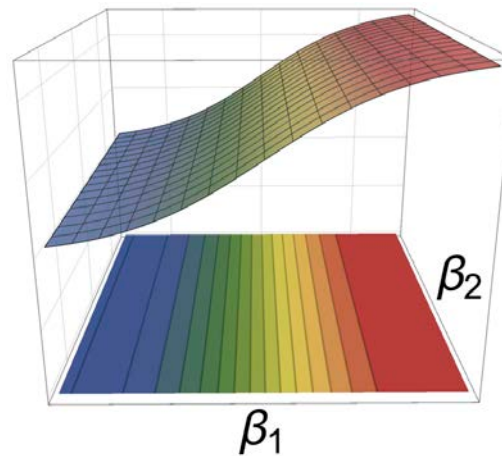
Objective: Choose Z to learn β “fast”

Bayesian Framework

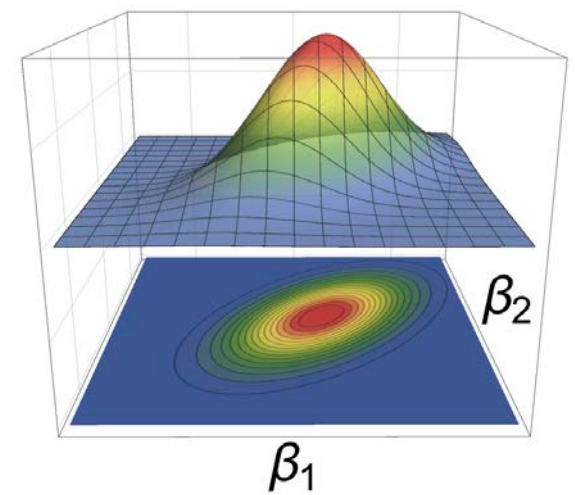
Prior distribution



Answer likelihood



Posterior distribution



$$\beta \sim N(\mu, \Sigma)$$

$$L(Y | \beta, Z)$$

$$g(\beta | Y, Z)$$

$$g(\beta | Y, Z) = \frac{\phi(\beta; \mu, \Sigma) L(Y | \beta, Z)}{\int_{\mathbb{R}} \phi(\beta; \mu, \Sigma) L(Y | \beta, Z) d\beta}$$

“fast” = minimize posterior “variance”

Goal = Minimize Expected Posterior Variance $f(Z)$

$$f(Z) = \mathbb{E}_Y \left\{ (\det \text{cov}(\beta | Y, Z))^{1/m} \right\}$$

Possible solution approaches:

$$g(\beta | Y, Z) \propto \phi(\beta; \mu, \Sigma) L(Y | \beta, Z)$$

$$I(\beta | Y, Z) := -\frac{\partial^2}{\partial \beta \partial \beta} \ln g(\beta | Y, Z) \propto \Sigma^{-1} - \frac{\partial^2}{\partial \beta \partial \beta} \ln L(Y | \beta, Z)$$

$$\text{cov}(\beta | Y, Z) \approx I(\hat{\beta} | Y, Z)^{-1}, \quad \mathbb{E}_{\beta \sim N(\mu, \sigma)} \left\{ I(\beta | Y, Z)^{-1} \right\}$$

$$\max_Z \mathbb{E}_Y \left\{ \left(\det I(\hat{\beta} | Y, Z) \right)^{1/m} \right\} \quad ?$$

A Really Good Case = Linear Regression

$$f(Z) = \mathbb{E}_Y \left\{ (\det \text{cov}(\beta | Y, Z))^{1/m} \right\}$$

$$y^i = \beta \cdot z^i + \epsilon_i, \quad \epsilon_i \sim N(0, 1)$$

$$g(\beta | Y, Z) = \phi(\beta; \mu', \Sigma')$$

$$\Sigma' = \text{var}(\beta | Y, Z) = (Z^T Z + \Sigma^{-1})^{-1}$$

$$\min_Z f(Z) = \max_Z (\det(Z^T Z + \Sigma^{-1}))^{1/m}$$

Z discrete \longrightarrow MISDP or MISOCP for $m = n$

A Relatively Good Case = Few Questions

$$f(Z) = \mathbb{E}_Y \left\{ (\det \text{cov}(\beta | Y, Z))^{1/m} \right\}$$

$$Z = \{z^i\}_{i=1}^q \subseteq \mathbb{R}^n, \quad q \ll n$$

$$\mathbb{E}(\beta | Y, Z) = m \left(Y, \{\mu \cdot z^i\}_{i=1}^q, \left\{ z^{iT} \sum z^j \right\}_{i,j=1}^q \right)$$

$$\text{cov}(\beta | Y, Z) = M \left(Y, \{\mu \cdot z^i\}_{i=1}^q, \left\{ z^{iT} \sum z^j \right\}_{i,j=1}^q \right)$$

$$f(Z) = f \left(\{\mu \cdot z^i\}_{i=1}^q, \left\{ z^{iT} \sum z^j \right\}_{i,j=1}^q \right)$$

A Relatively Good Case = Few Questions

$$f(Z) = \mathbb{E}_Y \left\{ (\det \text{cov}(\beta | Y, Z))^{1/m} \right\}$$

$Z =$

$\mathbb{E}(\beta)$

$\text{cov}(\beta)$

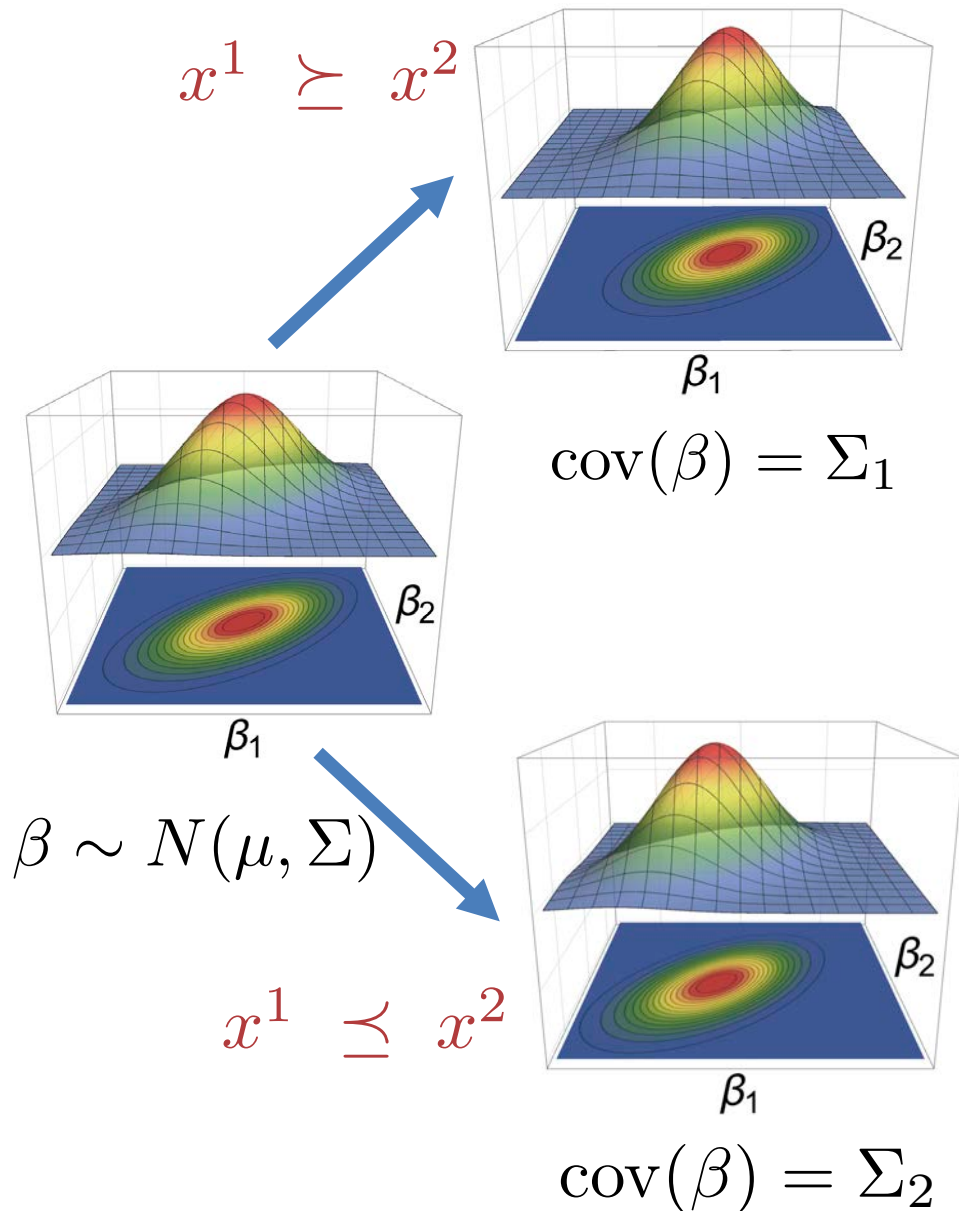
Only requirements:

- $\beta \sim N(\mu, \Sigma)$
- $L(Y | \beta, Z) = \prod_{i=1}^q h(y^i, \beta \cdot z^i)$

✓ Logistic regression with small q

$f(Z) = f\left(\left\{ \mu \cdot z \right\}_{i=1}^q, \left\{ z \cdot \Delta z^j \right\}_{i,j=1}^q\right)$

Question Selection for CBCA



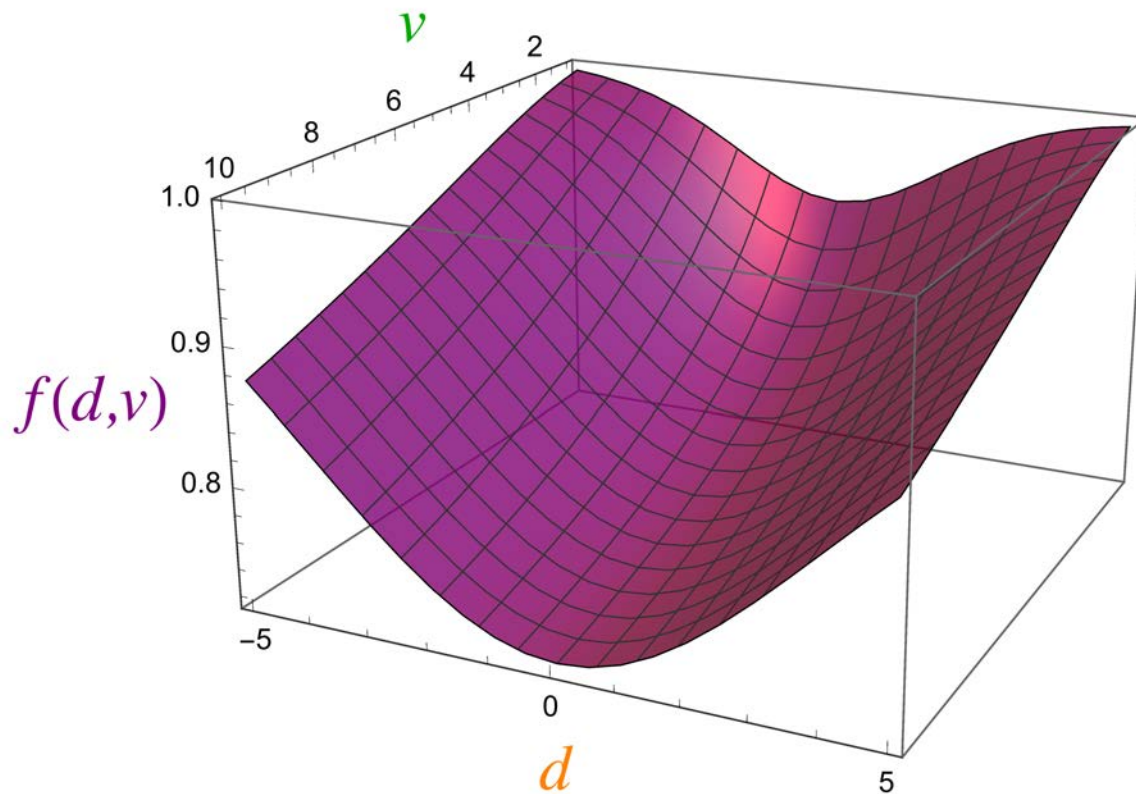
- “Variance” = D-Efficiency:
- $f(x^1, x^2) := \mathbb{E}_{\beta, x^1 \preceq/\succeq x^2} \left(\det(\Sigma_i)^{1/p} \right)$
- Non-convex function
- Without previous slide, even evaluation requires $\dim(\beta)$ - dimensional integration
-

D-efficiency Simplification for CBCA

- D-efficiency = Non-convex function $f(d, v)$ of

distance: $d := \mu \cdot (x^1 - x^2)$

variance: $v := (x^1 - x^2)' \cdot \Sigma \cdot (x^1 - x^2)$



Can evaluate $f(d, v)$
with 1-dim integral 😊

Simplification = Trade-off for known criteria

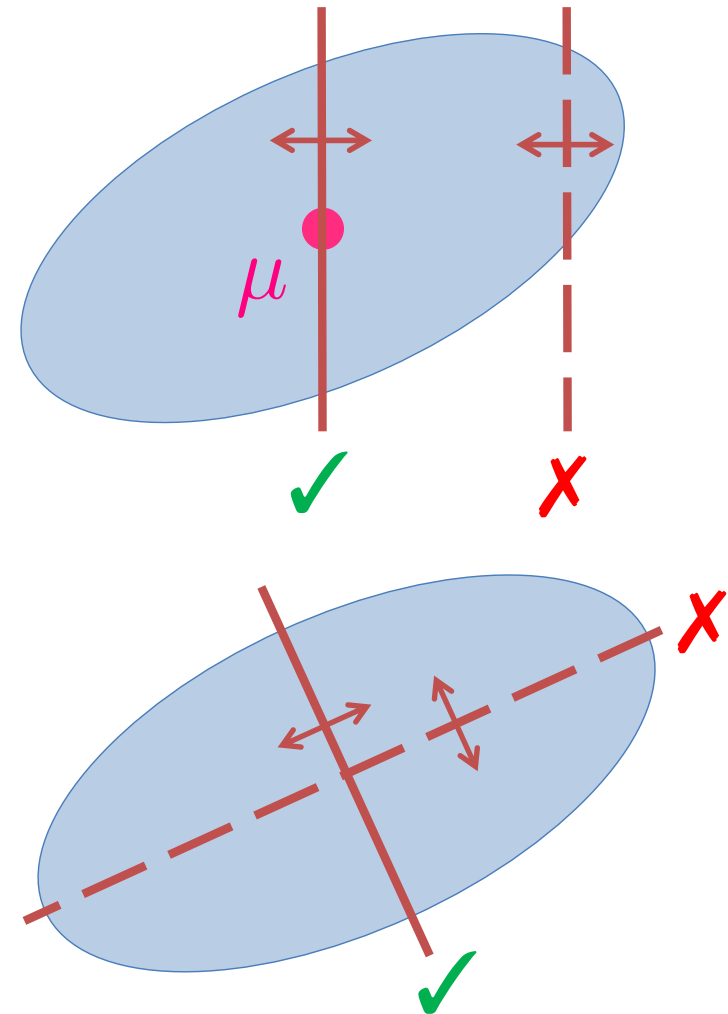
$$(\beta - \mu)' \cdot \Sigma^{-1} \cdot (\beta - \mu) \leq r$$

- Choice balance:
 - Minimize **distance** to center

$$\mu \cdot (x^1 - x^2)$$

- Postchoice symmetry:
 - Maximize **variance** of question

$$(x^1 - x^2)' \cdot \Sigma \cdot (x^1 - x^2)$$



Optimization Model

min

$$f(d, v)$$

~~X~~

s.t.

$$\mu \cdot (x^1 - x^2) = d \quad \checkmark$$

$$(x^1 - x^2)' \cdot \Sigma \cdot (x^1 - x^2) = v \quad \checkmark \text{ / } \times$$

$$A^1 x^1 + A^2 x^2 \leq b \quad \checkmark$$

linearize $x_i^k \cdot x_j^l$

$$x^1 \neq x^2 \quad \checkmark \text{ / } \times$$

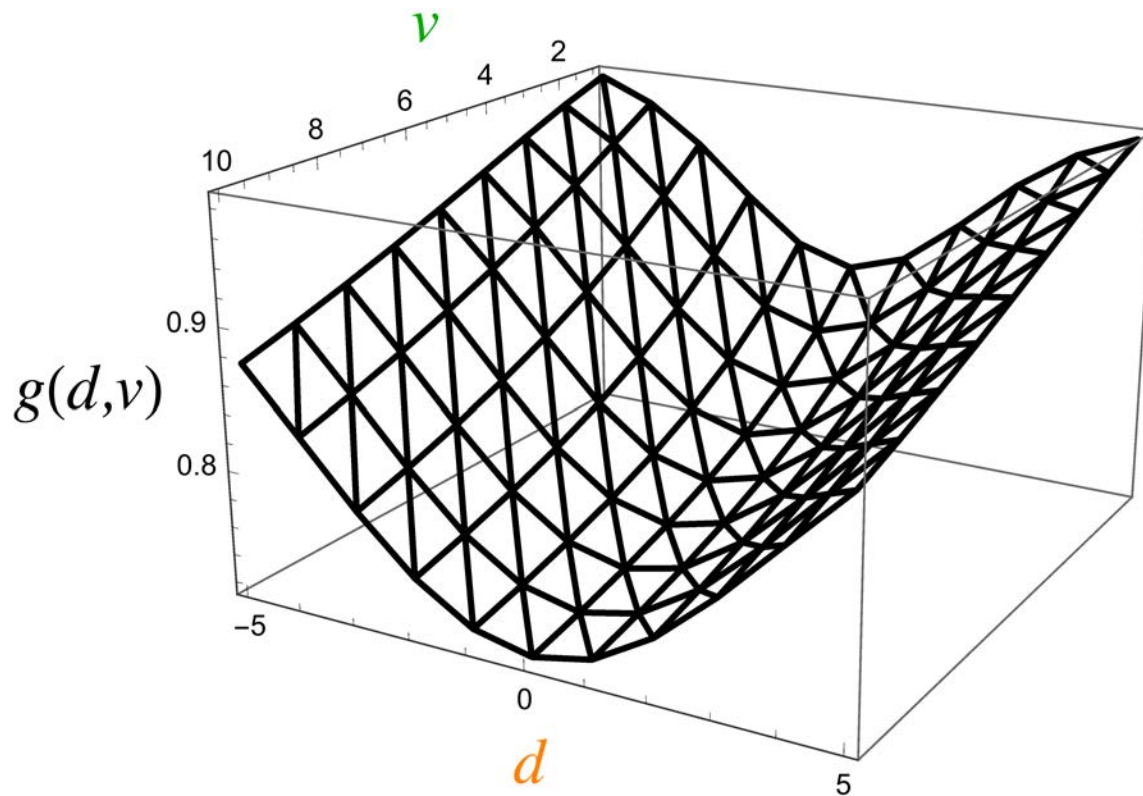
$$x^1, x^2 \in \{0, 1\}^n$$

Technique 2: Piecewise Linear Functions

- D-efficiency = Non-convex function $f(d, v)$ of

distance: $d := \mu \cdot (x^1 - x^2)$

variance: $v := (x^1 - x^2)' \cdot \Sigma \cdot (x^1 - x^2)$



Can evaluate $f(d, v)$
with 1-dim integral 😊

Piecewise Linear
Interpolation

MIP formulation

MIP-based Adaptive Questionnaires



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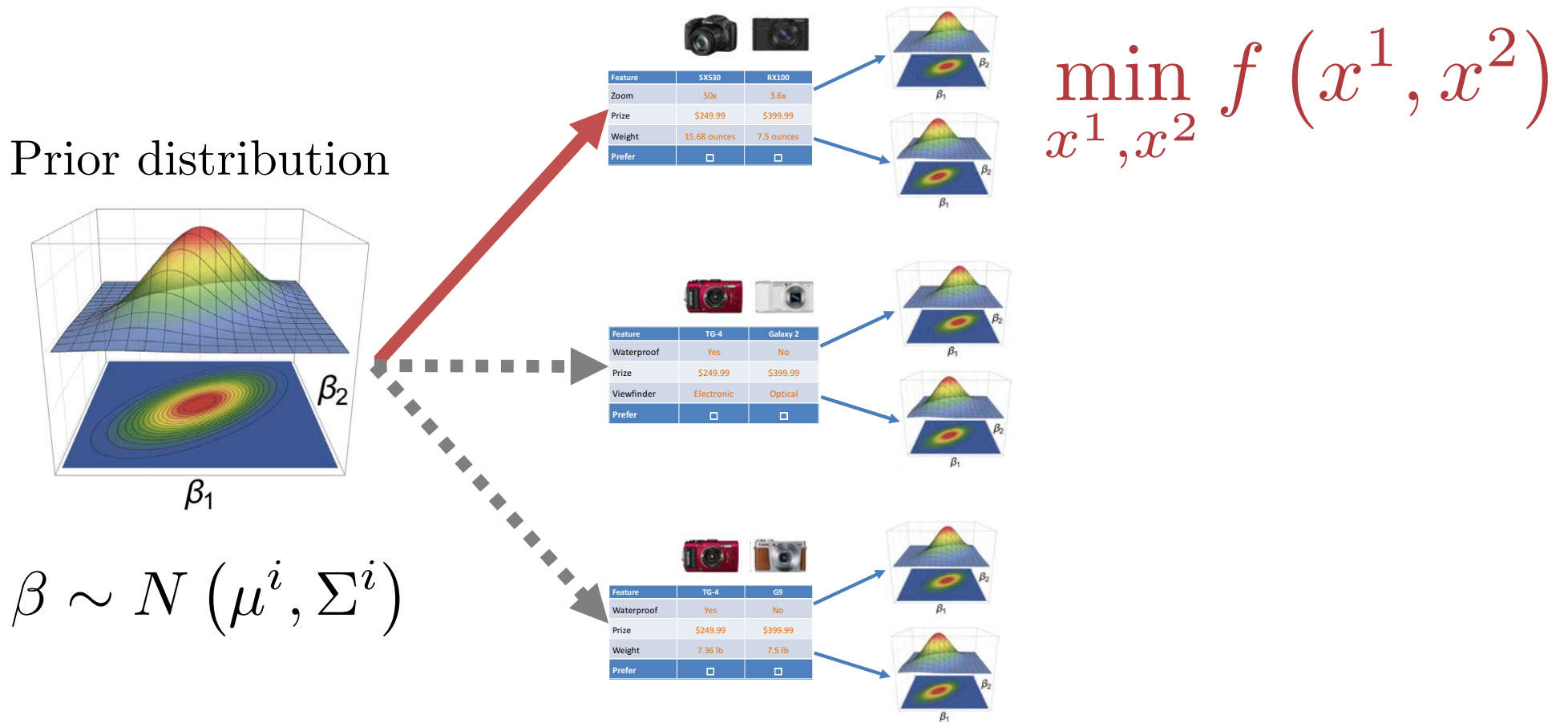
Feature	TG-4	Galaxy Z
Waterproof	Yes	No
Prize	\$249.99	\$399.99
Viewfinder	Electronic	Optical
Prefer	<input checked="" type="checkbox"/>	<input type="checkbox"/>

$$\mathbb{E} (\beta \mid Y, X^1, X^2)$$

$$\text{cov} (\beta \mid Y, X^1, X^2)$$

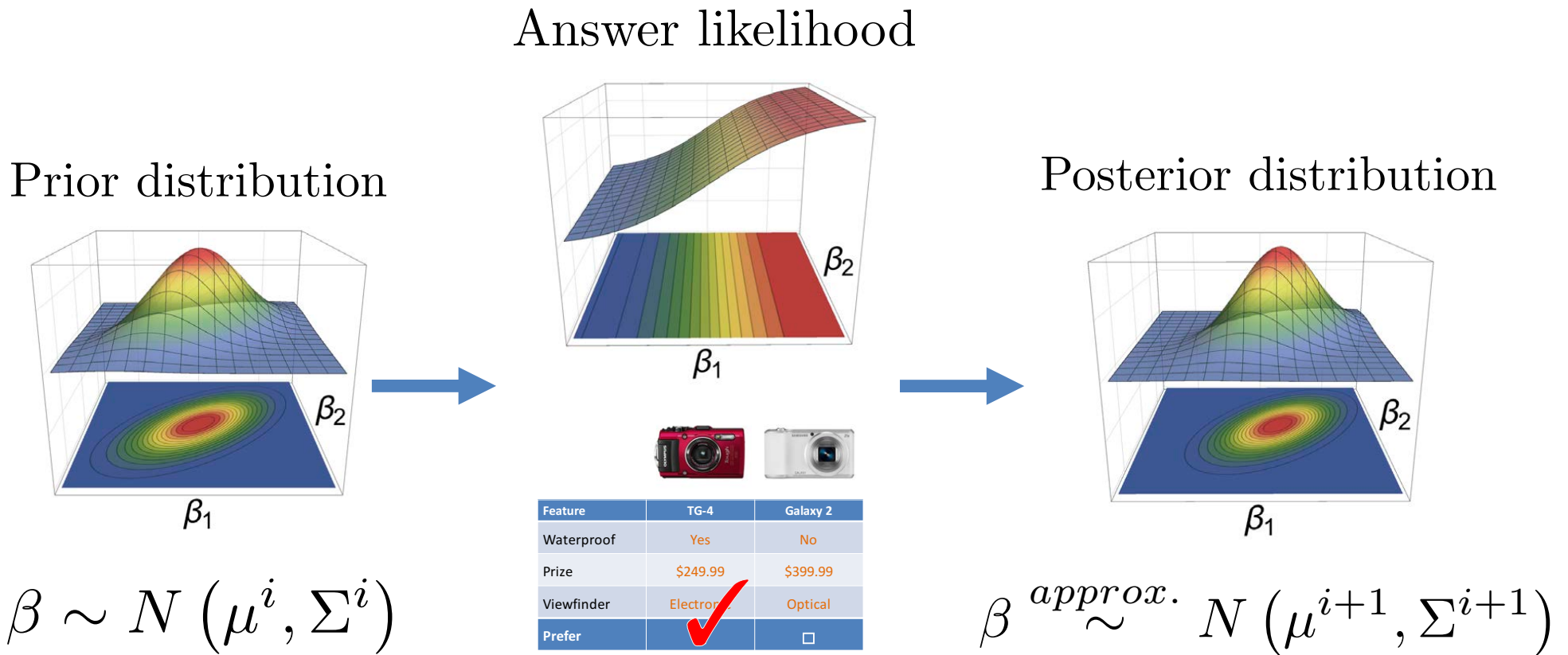
- Optimal one-step look-ahead moment-matching approximate Bayesian approach.

Optimal One-Step Look-Ahead



- Solve with MIP formulation

Moment-Matching Approximate Bayesian Update



- $\mu^{i+1} = \mathbb{E}(\beta | y, x^1, x^2)$
- $\Sigma^{i+1} = \text{cov}(\beta | y, x^1, x^2)$

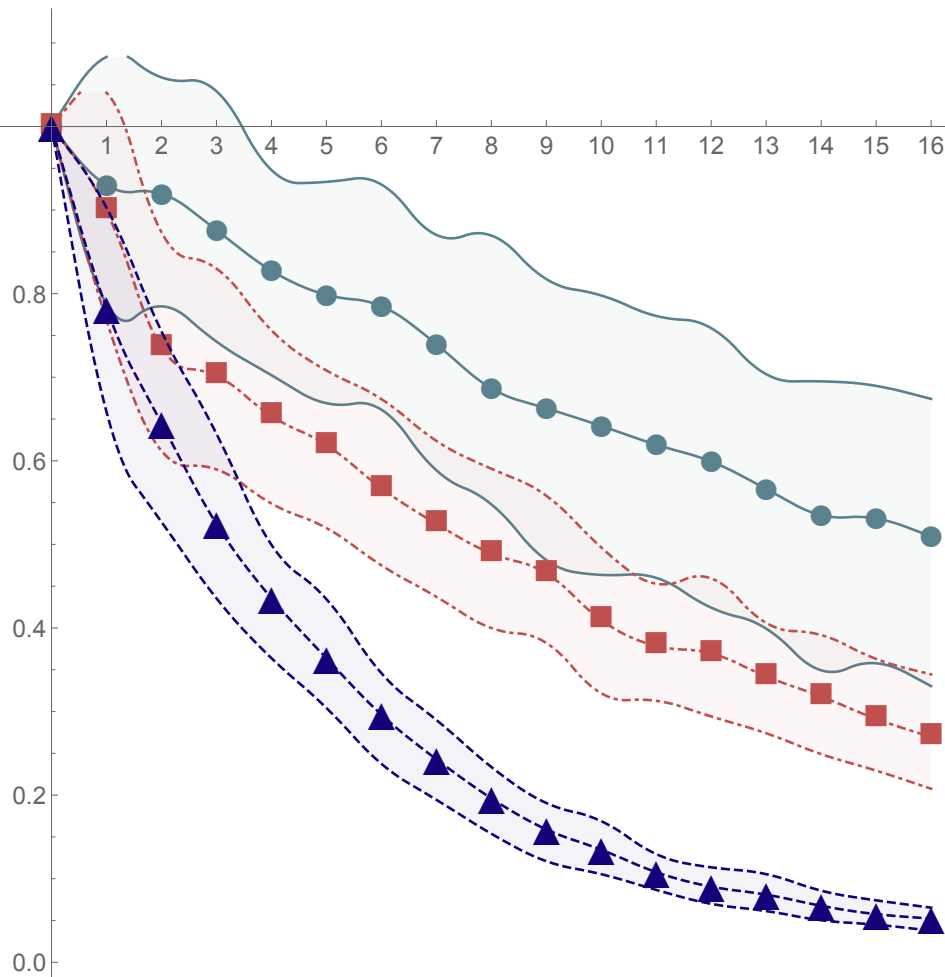
1-dim integral

Computational Experiments

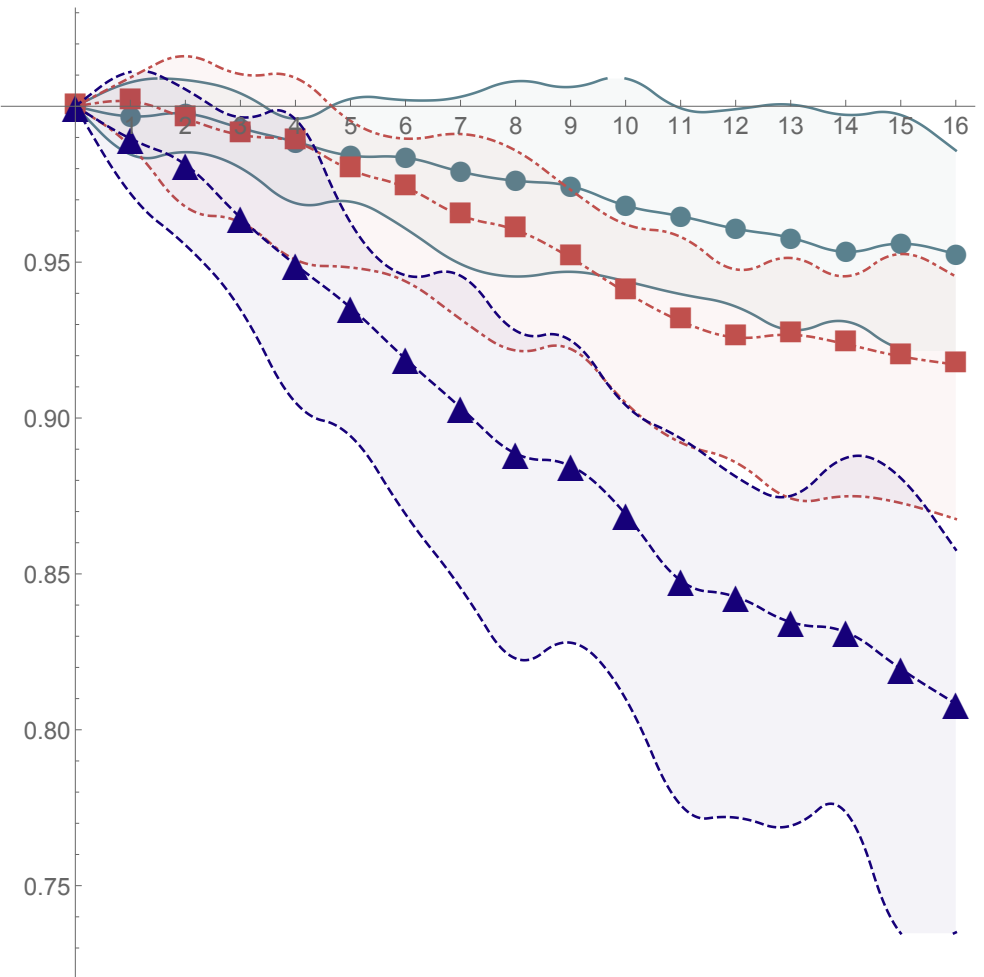
- 16 questions, 2 options, 12 and 24 features
- Simulate MNL responses with known β^*
- Question Selection
 - MIP-based using **CPLEX** and open source **COIN-OR** solver
 - Knapsack-based geometric **Heuristic** by Toubia et al.
- Time limits of 1 s and 10 s
- Metrics:
 - Estimator variance = $(\det \text{cov}(\beta | Y, X^1, X^2))^{1/2}$
 - Estimator distance = $\|\mathbb{E}(\beta | Y, X^1, X^2) - \beta^*\|_2$
 - Computed for true posterior with MCMC

Results for 12 Features, 1 s time limit

Estimator Variance



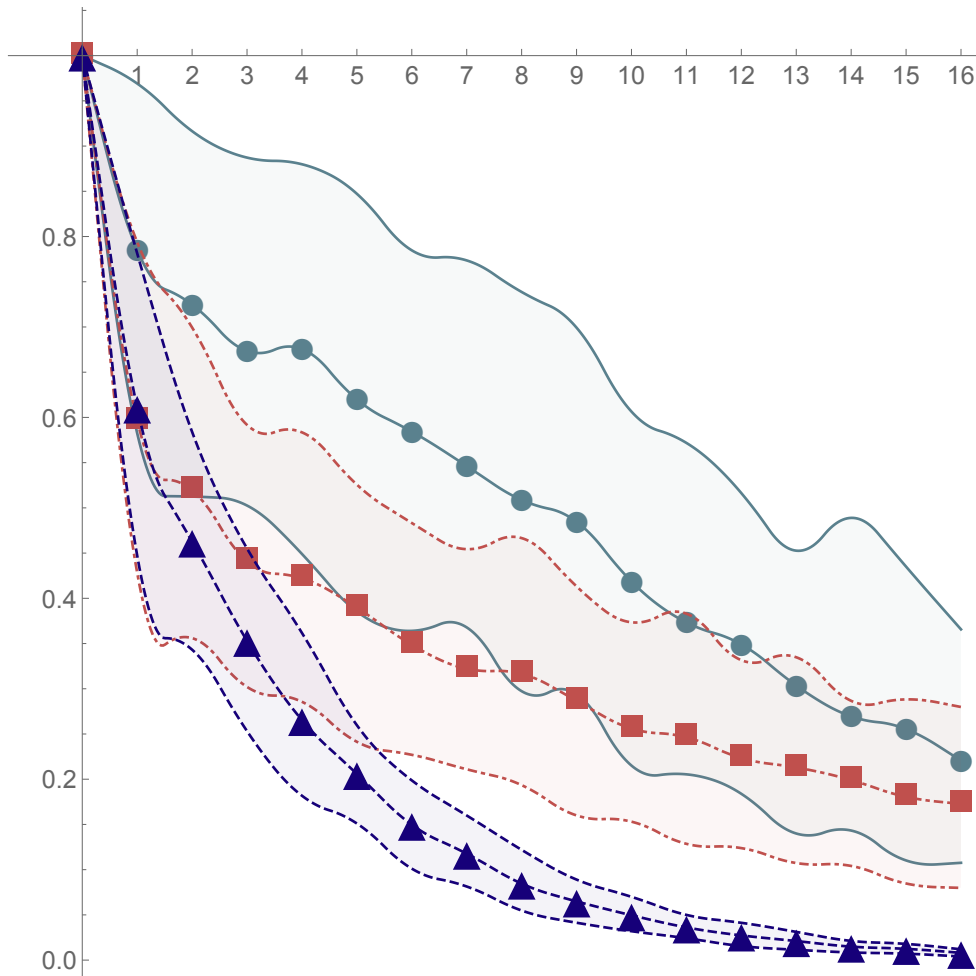
Estimator Distance



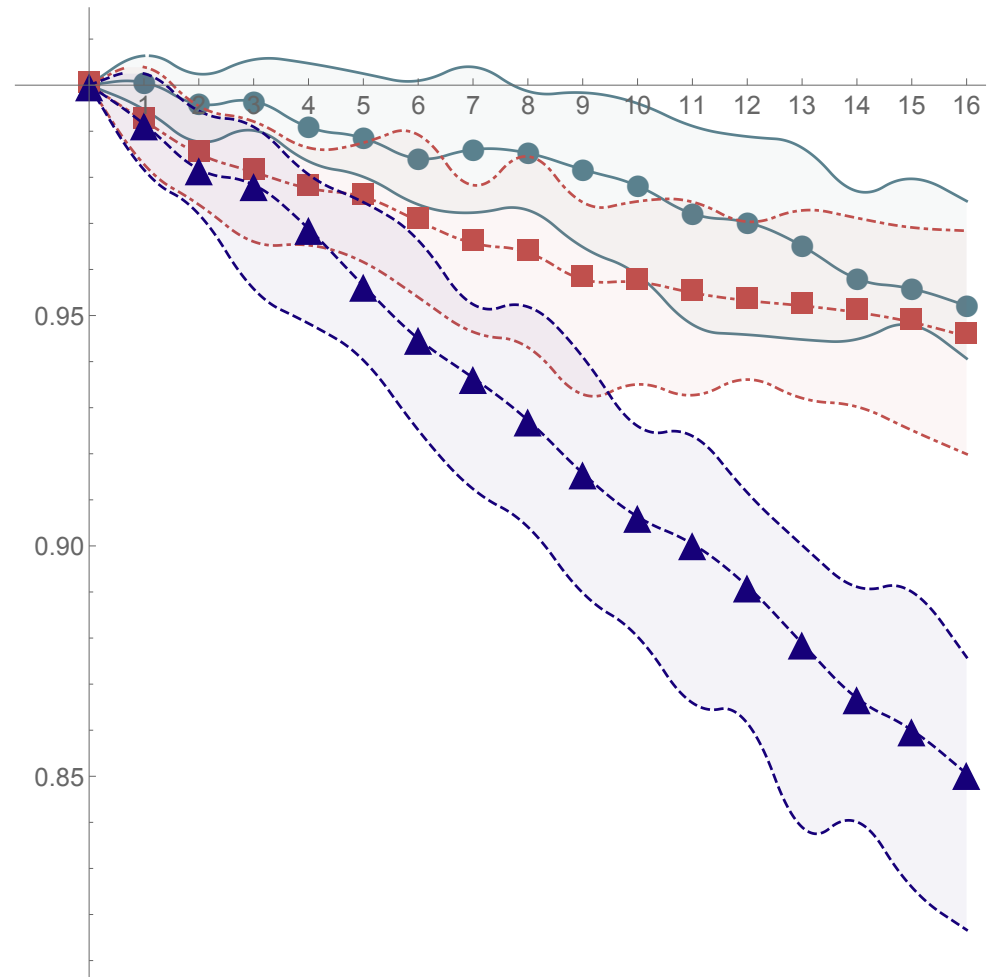
- Heuristic (Avg. = 0.04 s, Max = 0.61s)
- COIN-OR (Avg. = 0.93 s, Max = 1s)
- ▲ CPLEX (Avg. = 0.21 s, Max = 0.48s)

Does it Scale? Results for 24 features

Estimator Variance

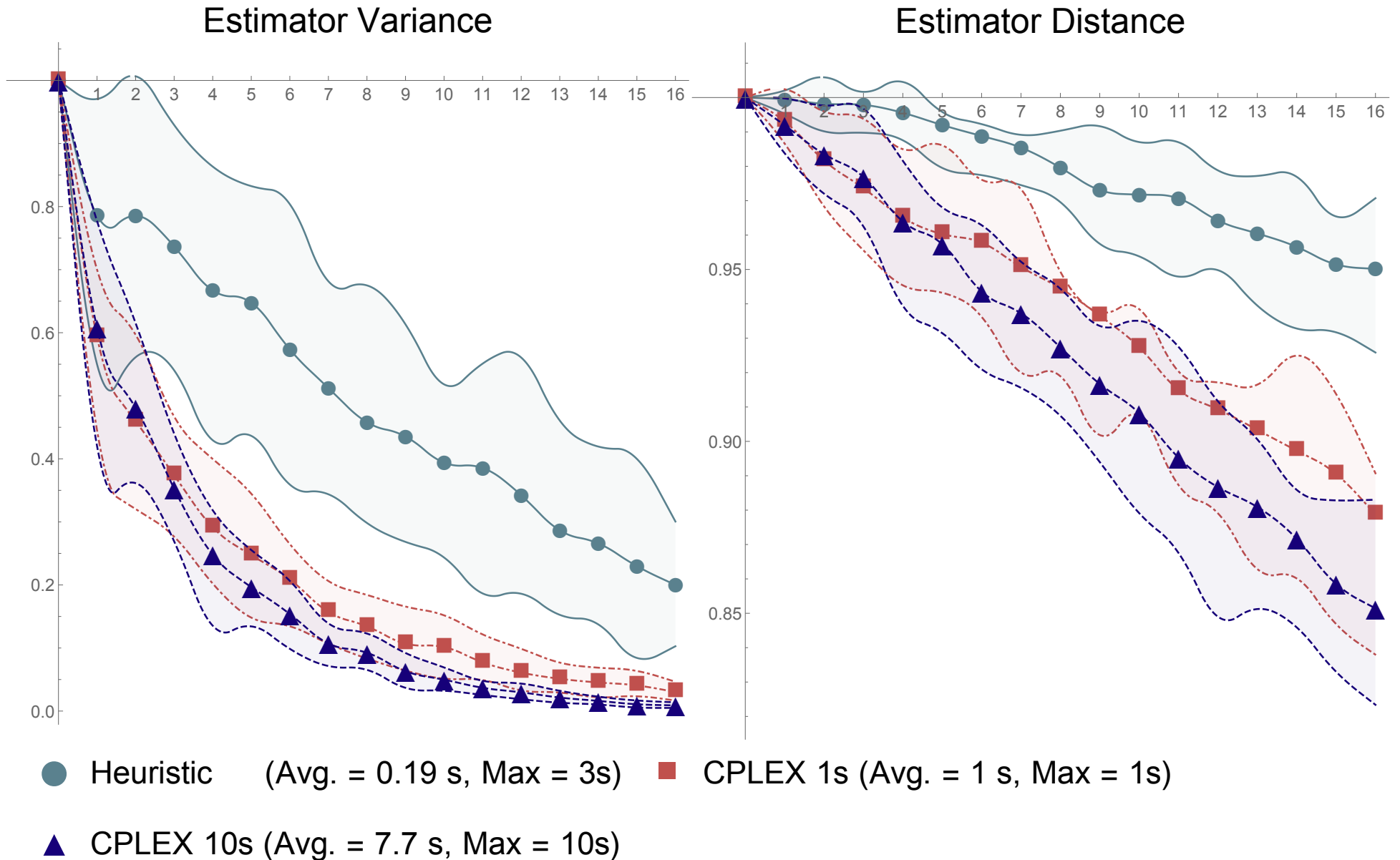


Estimator Distance



- Heuristic (Avg. = 0.19 s, Max = 3s)
- CPLEX 1s (Avg. = 1 s, Max = 1s)
- ▲ CPLEX 10s (Avg. = 7.7 s, Max = 10s)

Some improvements for 24 features



Summary and Main Messages



- Always choose Chewbacca!
- MIP can now “solve” challenging problems in practice
 - Even in near-real time
 - Appropriate domain expertise can be crucial for MIP’ing
 - Commercial solvers best, but free solvers reasonable
 - Integration into complex systems easy with JuMP
 - Some scalability : get the most out of “small” data
- Adaptive Choice-based Conjoint Analysis
 - Improves on existing **geometric** methods
 - <http://ssrn.com/abstract=2798984>