

Modeling Power of Mixed Integer Convex Optimization Problems And Their Effective Solution with Julia and JuMP

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Mixed Integer Convex Optimization (MICP)

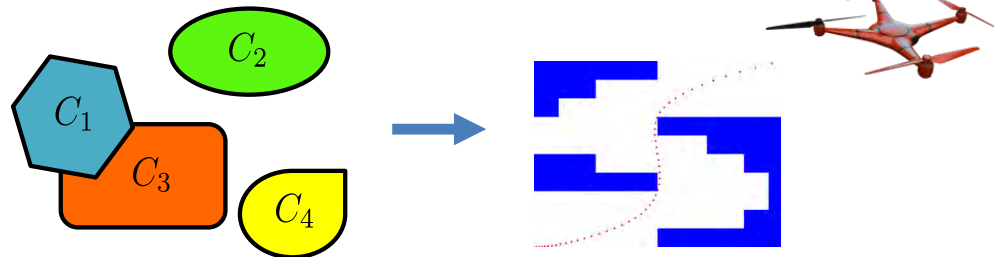
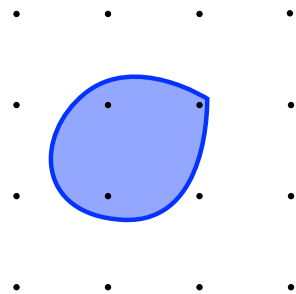
$$\min f(x)$$

s.t.

$$x \in C$$

$$x_i \in \mathbb{Z} \quad i \in I$$

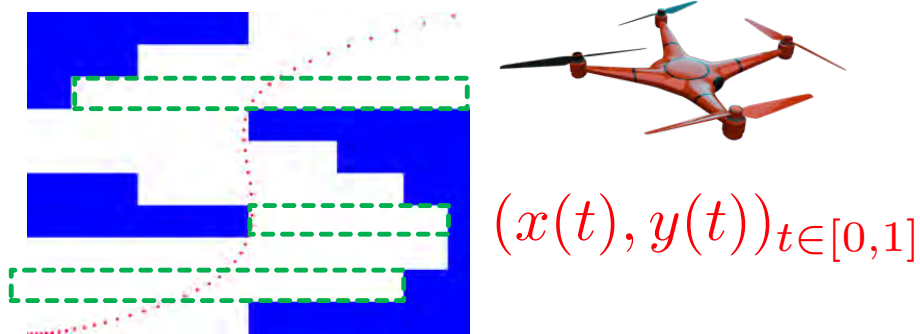
convex f and C .



<http://www.gurobi.com/company/example-customers>

A Mixed-Integer Infinite Dimensional Example

- Obstacle avoiding trajectory:



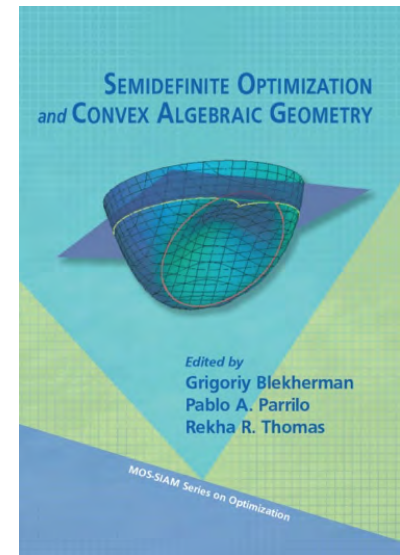
- Step 1: discretize time into intervals
 $0 = T_1 < T_2 < \dots < T_N$ s.t.
 $(x(t), y(t)) = p_i(t) \quad t \in [T_i, T_{i+1}]$
- Step 2: “safe polyhedrons”
 $P^r = \{x \in \mathbb{R}^2: A^r x \leq b^r\}$ s.t.
 $\forall i \exists r$ s.t. $p_i(t) \in P^r \quad t \in [T_i, T_{i+1}]$

- $p_i(t) \in P^r \rightarrow q_{i,r}(t) \geq 0 \quad \forall t$

SOS:

$$q_{i,r}(t) = \sum_j r_j^2(t)$$

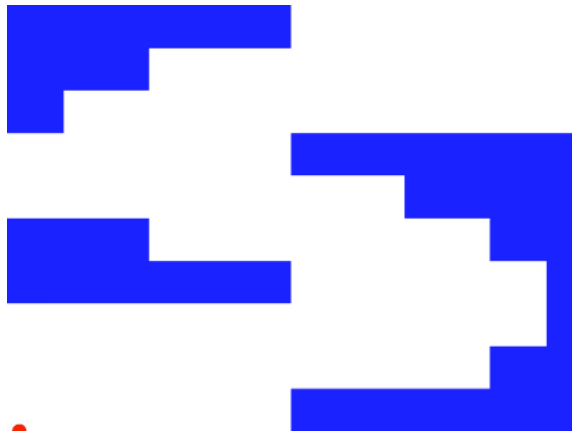
- Bound degree of polynomials:
Semidefinite Programming (SDP)
- MI-SDP solver:



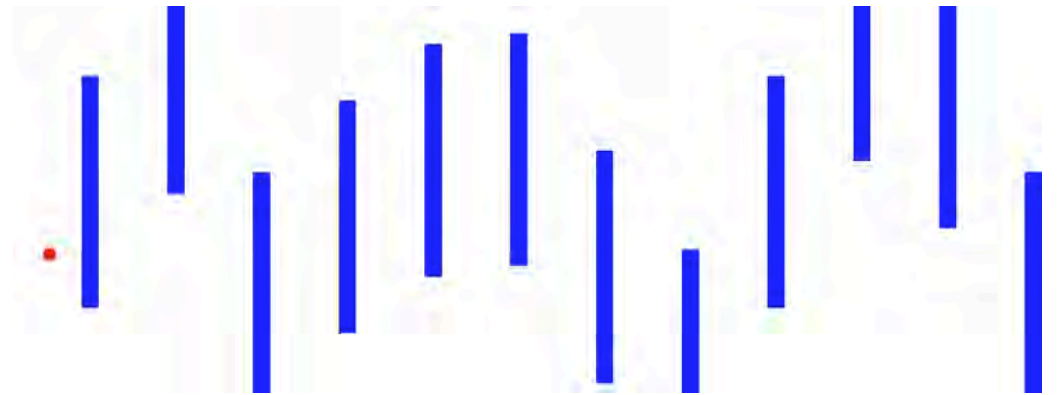
Solving MI-SDP to Global Optimality?



Optimal "Smoothness" in 651 seconds



Optimal "clicks" in 80 seconds



Outline

- **MICP Representability:** Characterize what can we model with MICP?
 - Joint work with M. Lubin and I. Zadik
- **Computational Solution of MICP:** Methods and Solvers based on



- MICP solvers is joint work with Joint work with R. Bent, C. Coey, I. Dunning, J. Huchette, L. Kapelevich, M. Lubin, E. Yamangil
- JuMP is joint work with and independent work by M. Lubin, I. Dunning, J. Huchette, B. Legat, O. Dowson, C. Coey, C. Coffrin, J. Dias Garcia, T. Koolen, V. Nesello, F. Pacaud, R. Schwarz, I. Tahiri, U. Worsøe,

What can we model with MICP?

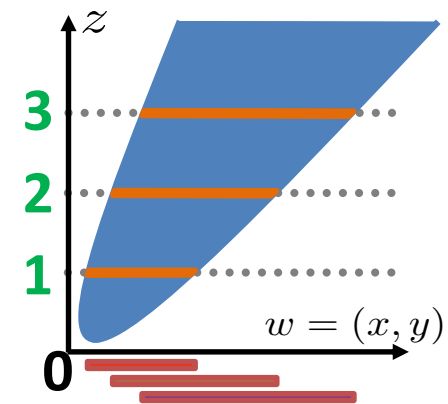
MICP /MICONV Formulations and Representability

- $S \subseteq \mathbb{R}^n$ is MICP representable (MICP-R) iff it has an MICP formulation:
 - A closed convex set $M \subseteq \mathbb{R}^{n+p+d}$
 - auxiliary continuous variables $y \in \mathbb{R}^p$
 - auxiliary integer variables $z \in \mathbb{Z}^d$

$$x \in S \iff \begin{aligned} &\exists (y, z) \in \mathbb{R}^p \times \mathbb{Z}^d \text{ s.t.} \\ &(x, y, z) \in M \end{aligned}$$

or equivalently

$$S = \text{proj}_x \left(M \cap \left(\mathbb{R}^{n+p} \times \mathbb{Z}^d \right) \right)$$



MICP-R \implies Countable Union of Projections of Closed Convex Sets

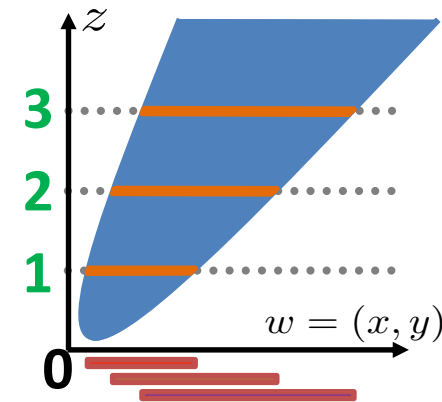
- $S \subseteq \mathbb{R}^n$ is MICP representable (MICP-R) iff it has an MICP formulation:
 - A closed convex set $M \subseteq \mathbb{R}^{n+p+d}$
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$$S = \bigcup_{z \in I \cap \mathbb{Z}^d} \text{proj}_x (B_z)$$

$$I = \text{proj}_z (M) \text{ convex}$$

$$B_z = M \cap (\mathbb{R}^{n+p} \times \{z\})$$

closed and convex



- Simple Proposition:
 - Complement of any convex body is a countable union of projections of closed convex sets

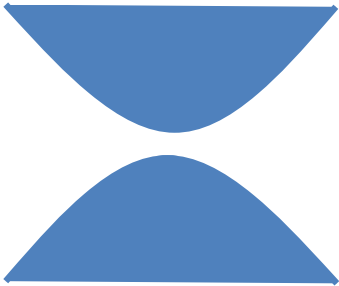
What Countable Unions are MICP-R? Jeroslow and Lowe Regularity

$$\exists \{r(i)\}_{i=1}^t \subseteq \mathbb{Q}^n \text{ s.t. } S = \bigcup_{i=1}^k P_i + \left\{ \sum_{i=1}^t \lambda_i r(i) : \lambda \in \mathbb{Z}_+^t \right\}$$

- Regularity Conditions:
 - M rational polyhedron $\Rightarrow P_i = \text{rational polytopes}$ (Jeroslow and Lowe '84):
 - $M = \{x \in \mathbb{Z}^2 : x_1 \cdot x_2 \geq \alpha\} \Rightarrow P_i = \text{points}$ (Dey & Moran '13)
 - $M = \text{Rational Polyhedron} \cap \text{“Rational” Ellipsoidal Cylinder} \Rightarrow P_i = \text{Rational Ellipsoid} \cap \text{Polytope}$ (Del Pia & Poskin '16)
 - $M = \text{Compact Convex} + \text{Rational Polyhedron Cone} \Rightarrow P_i = \text{Compact Convex}$ (Lubin, Zadik & V. 17')

What **Other** Countable Unions are MICP-R?

Two sheet hyperbola?



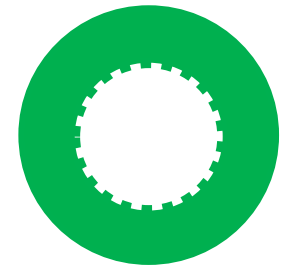
$$\{x \in \mathbb{R}^2 : 1 + x_1^2 \leq x_2^2\}$$

Spherical shell?



$$\{x \in \mathbb{R}^2 : 1 \leq \|x\| \leq 2\}$$

“Clopen” Spherical shell?



$$\{x \in \mathbb{R}^2 : 1 < \|x\| \leq 2\}$$

- Integer points in parabola $\{(x, x^2) : x \in \mathbb{Z}\}$?
- The set of $n \times n$ matrices with rank $\leq k$?
- **Dense discrete set?** $\{\sqrt{2}x - \lfloor \sqrt{2}x \rfloor : x \in \mathbb{N}\} \subseteq [0, 1]$
- Set of prime numbers?

"God made the integers, all else is the work of man"

- Leopold Kronecker

0-1 MICP = Finite Union of (Closed) Convex Sets

- T_1, \dots, T_k be **closed convex** set. Formulation of $x \in \bigcup_{i=1}^k T_i$:

$$(\mathbf{x}^i, z_i) \in \overline{\text{cone}}(T_i \times \{1\}) \quad \forall i \in [k]$$

$$\|\mathbf{x}^i\|_2^2 \leq z_i t_i \quad \forall i \in [k]$$

$$\sum_{i=1}^k \mathbf{x}^i = \mathbf{x},$$

$$\sum_{i=1}^k z_i = 1,$$

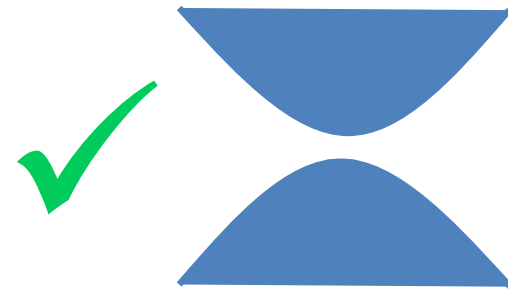
$$\mathbf{z} \in \{0,1\}^k,$$

$$t \in \mathbb{R}_+^k,$$

$$\mathbf{x}^i \in \mathbb{R}^n$$

$$\forall i \in [k]$$

Two sheet hyperbola?



$$\{x \in \mathbb{R}^2 : 1 + x_1^2 \leq x_2^2\}$$

A Simple Lemma for non-MICP Representability

- Obstruction for MICP representability of S :

$$\text{infinite } R \subseteq S \quad \text{s.t.} \quad \frac{u+v}{2} \notin S \quad \forall u, v \in R, u \neq v$$

- Proof: Assume for contradiction there exists M such that:

$$S = \text{proj}_x (M \cap (\mathbb{R}^{n+p} \times \mathbb{Z}^d))$$

$$\begin{aligned} (u, y_u, z_u) \in M \\ (v, y_v, z_v) \in M \end{aligned} \implies \frac{z_u + z_v}{2} \notin \mathbb{Z}^d$$

$$z_u \equiv z_v \pmod{2} \text{ component-wise} \implies \frac{z_u + z_v}{2} \in \mathbb{Z}^d$$

$$\text{component-wise parity classes} = 2^d < |R| = \infty \quad \implies \text{contradiction}$$

A Simple Lemma for non-MICP Representability

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Spherical shell?



$$\{x \in \mathbb{R}^2 : 1 \leq \|x\| \leq 2\}$$

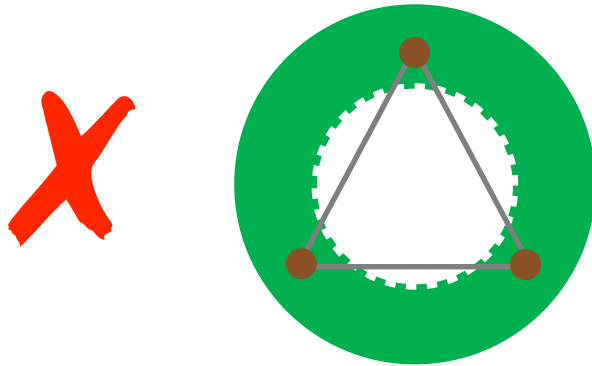
- ✗ Integer points in parabola $\{(x, x^2) : x \in \mathbb{Z}\}$?
- ✗ The set of $n \times n$ matrices with $\text{rank} \leq k$?
- ✗ Set of prime numbers?

A Simple Lemma for non-MICP Representability

$$R \subseteq S \quad \text{s.t.} \quad \frac{u+v}{2} \notin S \quad \forall u, v \in R, u \neq v \quad |R| = k$$

- MICP formulation of S needs $\log_2 k$ variables :

“Clopen” Spherical shell?



Arbitrarily large R

$$\{x \in \mathbb{R}^2 : 1 < \|x\| \leq 2\}$$

What About Irrationality?

- A **set** S is **periodic** if and only if:

$$\exists r \in \mathbb{R}^n \setminus \{\mathbf{0}\} \quad \text{s.t.} \quad x + \lambda r \in S \quad \forall \lambda \in \mathbb{Z}_+, x \in S$$

- Non-periodic MICP-R sets

– **Dense discrete set** $\left\{ \sqrt{2}x - \lfloor \sqrt{2}x \rfloor : x \in \mathbb{N} \right\} \subseteq [0, 1]$

$$\|(z_1, z_1)\|_2 \leq z_2 + 1, \quad \|(z_2, z_2)\|_2 \leq 2z_1, \quad x_1 = y_1 - z_2,$$

$$\|(z_1, z_1)\|_2 \leq y_1, \quad \|(y_1, y_1)\|_2 \leq 2z_1, \quad z \in \mathbb{Z}^2$$

– **Set of naturals** $\left\{ x \in \mathbb{N} : \sqrt{2}x - \lfloor \sqrt{2}x \rfloor \notin (\varepsilon, 1 - \sqrt{2}\varepsilon) \right\}$

$$\|(x_1, x_1)\|_2 \leq x_2 + \varepsilon, \quad \|(x_2, x_2)\|_2 \leq 2x_1 + 2\varepsilon, \quad x \in \mathbb{Z}_+^2$$

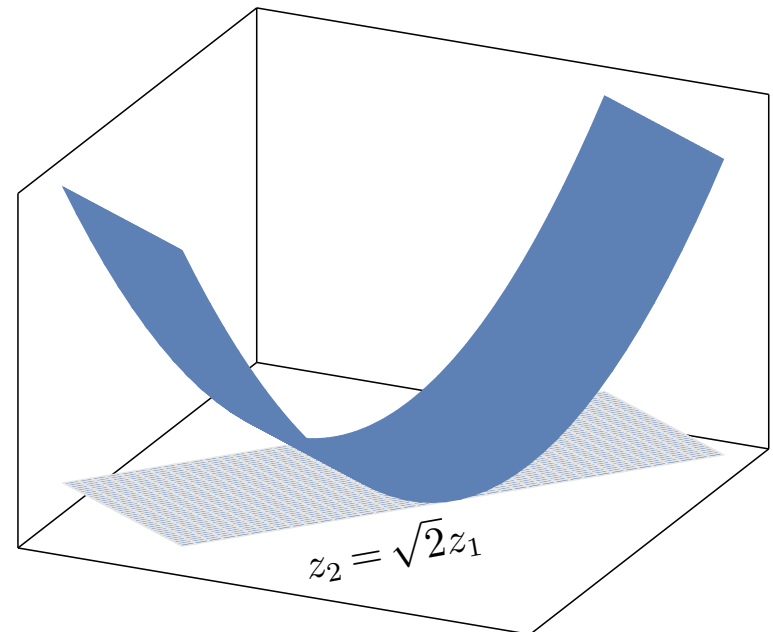
A Definition of Rational MICP-R

$$S = \bigcup_{z \in I \cap \mathbb{Z}^d} \text{proj}_x (B_z)$$

$$S = \text{proj}_x (M \cap (\mathbb{R}^{n+p} \times \mathbb{Z}^d))$$

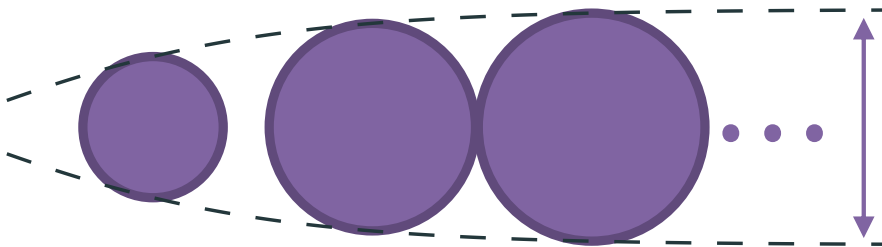
$$I = \text{proj}_z (M)$$

- Any rational affine mapping of index set I :
 - Is bounded, or
 - Has an integer (rational) recession direction
- Irrational directions can hide!



Properties of Rational MICP-R Sets

- A **rational MICP-R** set \mathcal{S} is a **finite union** of **convex** or **periodic** sets if
 - \mathcal{S} is **closed** and its **convex subsets** have **upper bounded diameter**
 - \mathcal{S} is a **not necessarily closed discrete** set
 - **Dense discrete** and **non-periodic naturals NOT R-MICPR**



Properties of Rational MICP-R Sets

- Other consequences:

- **Compact rational MICP-R :**

- **finite unions** of **compact convex** sets

- **Rational MICP-R** subsets of the **naturals** =

- **Union** of **finite** points and **one periodic** set

- **Union** of **finite** points and **one MILP-R** set

$$\{p_i\}_{i=1}^k \cup \{a \cdot t + b : t \in \mathbb{Z}_+\}$$

- **Rational MICP Representability:**

- **Closed** under: **Finite Union, Cartesian Product, rational affine transformations and Minkowski sum**

- **NOT Closed** under **Intersection**.

Rational MICP-R does Not Imply Finite Shapes



- There exists an increasing function h such that:
 - $P_z \subseteq \mathbb{R}^2$ regular $h(z)$ -gon centered at $(z, 0)$
 - $P_z \cap P_{z'} = \emptyset, \quad z \neq z'$
 - $S = \bigcup_{z=1}^{\infty} P_z$ is R-MICPR and periodic
- Equal volume \Rightarrow Finite # of Shapes

MICP with



&



50+ Years of MIP = Significant Solver Speedups

- Algorithmic Improvements (**Machine Independent**):

– **CPLEX** →  → 

- v1.2 (1991) – v11 (2007): **29,000 x** speedup

–  **GUROBI**
OPTIMIZATION

- v1 (2009) – v6.5 (2015): **48.7 x** speedup

→ **≈ 1.9 x / year**

- Also MICP:

–  **GUROBI**
OPTIMIZATION

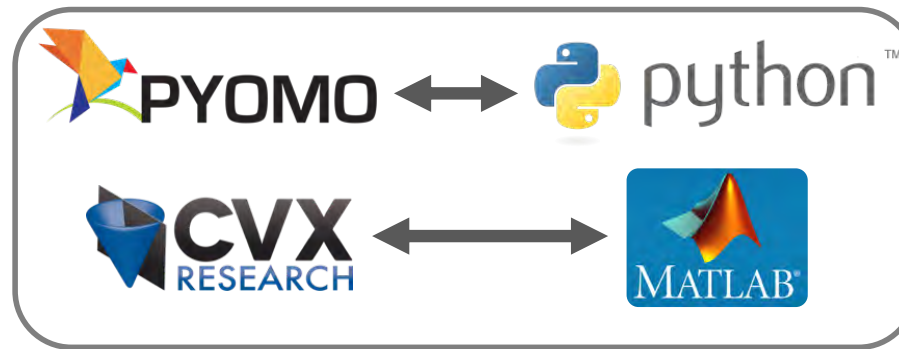
- v6.0 (2014) – v6.5 (2015) quadratic: **4.43 x**
(V., Dunning, Huchette, Lubin, 2015)

Accessing MIP Solvers = Modelling Languages

- User-friendly algebraic modelling languages (AML):

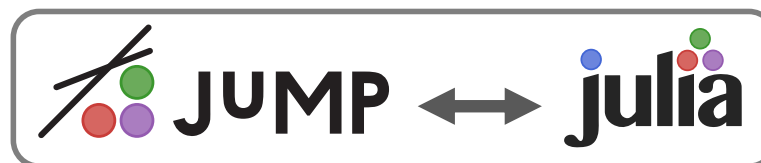


Standalone and Fast



Based on General Language and Versatile

- Fast and Versatile, but complicated (and possibly proprietary)
 - Low-level C/C++ solver or Coin-OR interfaces & frameworks
- Best of all worlds?



21st Century Programming/Modelling Languages



- Open-source and free!
- “Floats like python/matlab, stings like C/Fortran”
- Petaflop scaling: C/C++, Fortran and Julia!
- Powerful **compiler** and **meta-programming** features



- Open-source and free!
- Modelling language, interface and software ecosystem for optimization (~20 solvers)
- **Easy to use**, **fast** and advanced
- Integrated into Julia

Large Software Stack and Vibrant Community



juliacon 2018

University College London



JuliaCon is coming to Baltimore

Monday 22nd to Friday 26th of July, 2019
at the University of Maryland Baltimore (UMB),
Baltimore, MD, USA



Large Software Stack and Vibrant Community



JuMP Developers Workshop

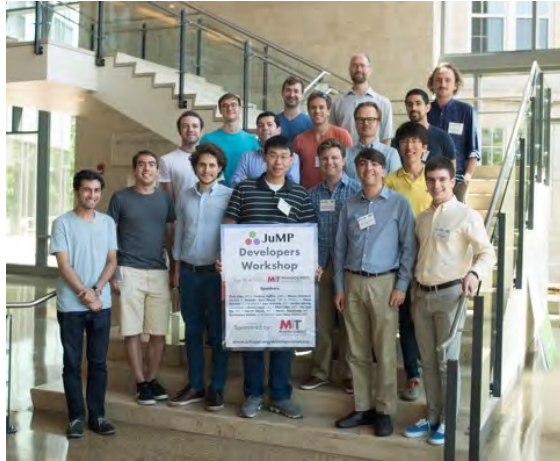
June 12-16, 2017, MIT MANAGEMENT SLOAN SCHOOL

Speakers

Chris Coey, MIT • Carleton Coffrin, LANL • Steven Diamond, Stanford • Joaquim Dias Garcia, PSR & PUC-Rio • Oscar Dowson, U. of Auckland • Joey Huchette, MIT • Jordan Jarvis, UW-Madison • Benoît Legat, UCL • Miles Lubin, MIT • Yee Sian Ng, MIT • Jarrett Revels, MIT • Nestor Sepulveda, MIT • Bartolomeo Stellato, U. of Oxford • Juan Pablo Vielma, MIT

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www.juliaopt.org/developersmeetup




THE SECOND ANNUAL JUMP-dev WORKSHOP

June 27-29, 2018, Institut de Mathématiques de Bordeaux

Speakers

Martin Biel, KTH • Oscar Dowson, U. of Auckland • Joaquim Dias Garcia, PSR & PUC-Rio • Hassan Hijazi, LANL • Jean-Hubert Hours, Arielys • Oliver Huber, UW-Madison • Joey Huchette, MIT • Ole Kroger, Uni Hohenheim • Benoît Legat, UCLouvain • Miles Lubin, Google • Guillaume Marquis, U. de Bordeaux • Harsha Nagarajan, LANL • François Pacaud, CERMICS, ENPC • Abel Soares Siqueira, Federal University of Paraná • Julie Silwák, RTE • Mohamed Tarek, UNSW Canberra • Matthew Wilhelm, U. of Connecticut • Ulf Wörzner, Mosek

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www.juliaopt.org/meetings/bordeaux2018




3RD ANNUAL JUMP-dev WORKSHOP

March 12-14, 2019

ESCUOLA DE INGENIERÍA PONTIFICIA UNIVERSIDAD CATÓLICA DE CHILE | Instituto Chileno Norteamericano

Chris Coey MIT	Lea Kapelevich MIT	David Sanders U. Nacional Autónoma de México
Joaquim Dias Garcia PSR & PUC-Rio	Stefan Karpinski Julia Computing	Thuener Silva PUC-Rio
Oscar Dowson Northwestern U.	Tomas Lagos González U. de Chile	Alessandro Soares PSR
Marcelo Forets UdelaR	José Daniel Lara UC Berkeley & NREL	Mario Souto PUC-Rio
Michael Garstka U. of Oxford	Benoît Legat UCLouvain	Mathieu Tanneau Polytechnique Montréal
Alvaro González Skoltech	Miles Lubin Google	Tillmann Weisser Los Alamos N. L.
Joey Huchette Google & Rice U.	Harsha Nagarajan Los Alamos N. L.	Andrew David Warner Roseberg PUC-Rio
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www.juliaopt.org/meetings/santiago2019



State-of-the- JUMP

- NumFOCUS Sponsored project since 2018
- NSF funding for annual meeting until 2023 (OAC-1835443)
- Hoping to have the first 3 GSoC students under NumFOCUS umbrella in 2019
- Towards v1.0 (see Miles talk at JuMP-dev):
 - v0.19 released on February 2019:
 - ~2 year and ~30,000 lines of code
 - To-do: Documentation, usability and regressions from v0.18



Google
Summer of Code

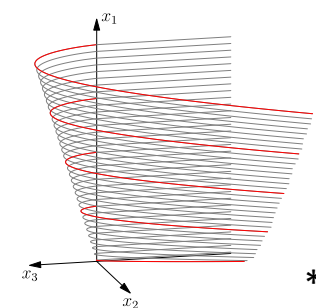
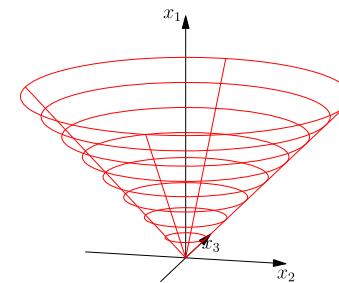
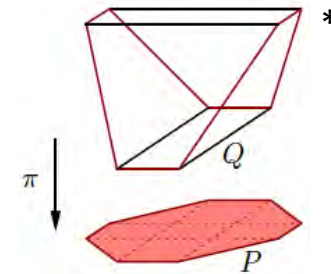
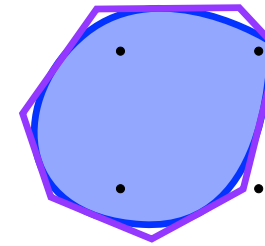
TOS: M. Lubin, I. Dunning & J. Huchette
Next-Gen: B. Legat & O. Dowson
Contributors: C. Coey, C. Coffrin, J. Dias Garcia, T. Koolen, V. Nesello, F. Pacaud, R. Schwarz, I. Tahiri, J. P. Vielma, U. Worsøe

Polyhedral Outer-Approximation for MICP Solvers

- Dynamically approximate **convex constraints** with **polyhedral** to combine **MILP** and **convex solvers**
 - Basis for most commercial & open source solvers
- Performance keys:
 1. Use power of **projection** to build **extended** or **lifted polyhedral** relaxations
 2. Exploit **geometry** and **duality** from **Conic Programming** (SOCP, SDP, etc.):

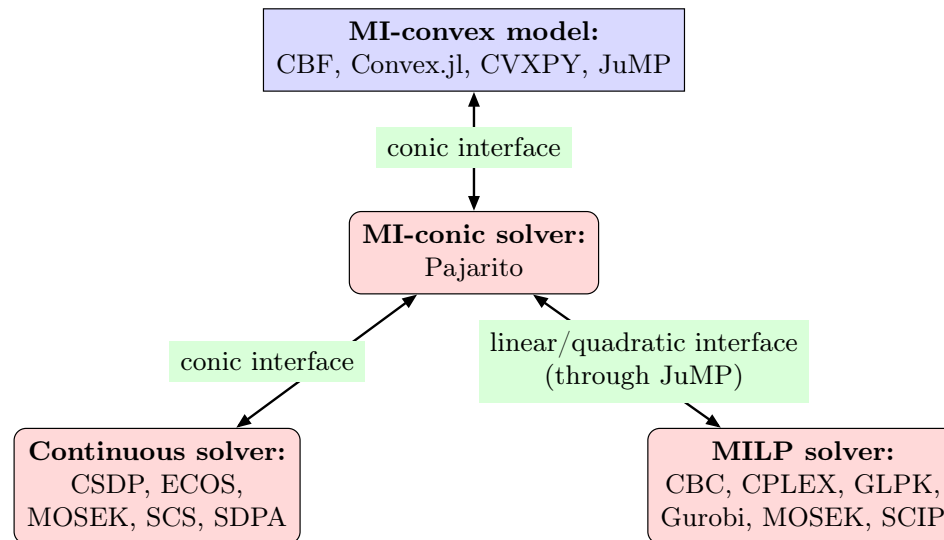
$$\min_{\mathbf{x} \in \mathbb{R}^N} \langle \mathbf{c}, \mathbf{x} \rangle : \mathbf{b}_k - \mathbf{A}_k \mathbf{x} \in \mathcal{C}_k, x_i \in \mathbb{Z}$$

For closed convex cones \mathcal{C}_k





* <https://rjlipton.wordpress.com>, ** MOSEK Modelling Cookbook

Pajarito: A Julia-based MICONIC Solver



- Solved gams01, tls5 and tls6 (MINLPLIB2)
- Fastest “open-source” MISOCP solver:
 - faster than Bonmin nearly matches SCIP
- Improves performance & reliability of CPLEX

Stability of CONIC Interior Point Algorithms is KEY!

- Why? Avoid non-differentiability issues? Stronger theory?
- Industry change in 2018:
 -  version 11.0 adds support for SOCP constraints
 -  version 9.0 deprecates nonlinear formulations

$$\begin{array}{ll} \min & f(x) \\ \text{subject to} & g(x) \leq 0, \end{array}$$

and focuses on pure conic (linear, SOCP, rotated SOCP, SDP, exp & power)

Hypatia: Pure Julia-based IPM Beyond “Standard” Cones

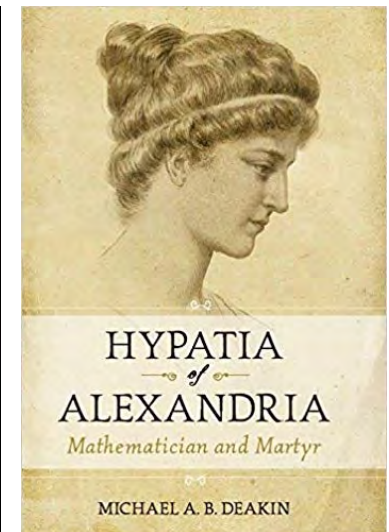
- A homogeneous interior-point solver for nonsymmetric cones (based on Skajaa and Ye '15, Papp and Yildiz '17, Andersen, Dahl, and Vandenberghe '04-18)
- Cones:
 - LP, SOCP, RSOCP, 3-dim exponential cone, PSD, L_∞ , n-dim power cone, spectral norm, log-Det cone,...
 - Sum-of-Squares, “Matrix” Sum-of-Squares, SOCP Sum-of-Squares, ...
- Customizable: “Bring your own barrier”



Chris Coey



Lea Kapelevich



Summary

- MICP can model many problems (but not all)
- How to solve MICP? Don't solve MICP, solve MICONIC
- Easy access to optimization modeling and solvers with
- Advanced solver development with Julia &

