

Discrete Geometry for Small and Strong Mixed Integer Programming Formulations

Juan Pablo Vielma

Massachusetts Institute of Technology

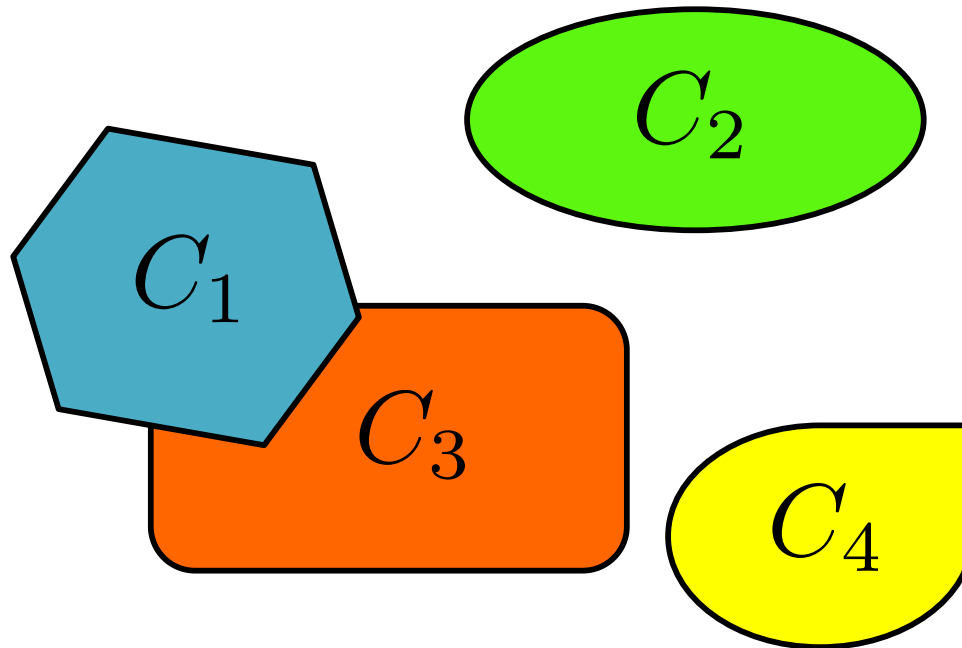
Seventh Cargèse Workshop on Combinatorial Optimization,
Institut d'Etudes Scientifiques de Cargèse,
Corsica (France). October, 2016.

Supported by NSF grant CMMI-1351619

Nonlinear Mixed 0-1 Integer Formulations

- Modeling Finite Alternatives = Unions of Convex Sets

$$x \in \bigcup_{i=1}^n C_i \subseteq \mathbb{R}^d$$



Extended and Non-Extended Formulations for $\bigcup_{i=1}^n C_i$

$$C_i = \{x \in \mathbb{R}^d : A^i x \leq b^i\}$$

Extended

$$\begin{aligned} A^i x^i &\leq b^i y_i && \forall i \in [n] \\ \sum_{i=1}^n x^i &= x \\ \sum_{i=1}^n y_i &= 1 \\ y &\in \{0, 1\}^n \\ x, x^i &\in \mathbb{R}^d && \forall i \in [n] \end{aligned}$$

Small? and strong (**ideal***)

Non-Extended

$$\begin{aligned} A^i x - b^i &\leq M_i (1 - y_i) && \forall i \in [n] \\ \sum_{i=1}^n y_i &= 1 \\ y &\in \{0, 1\}^n \\ x &\in \mathbb{R}^d && \forall i \in [n] \end{aligned}$$

Small, but weak?

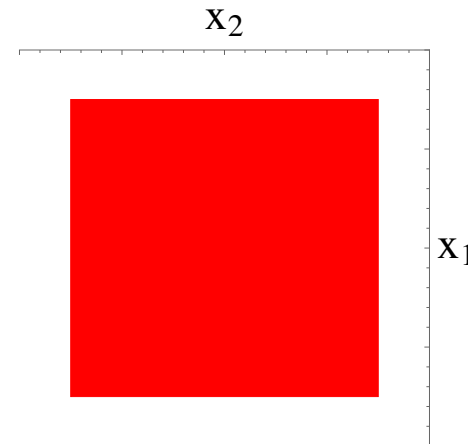
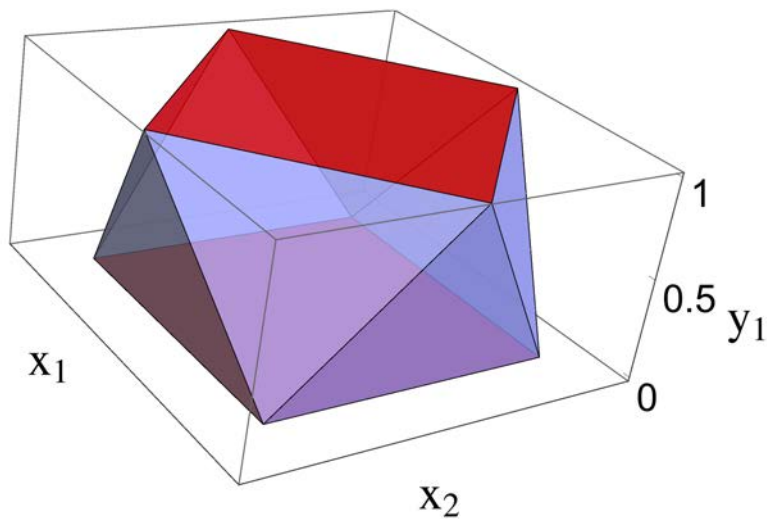
*Integral y in extreme points of LP relaxation

Outline

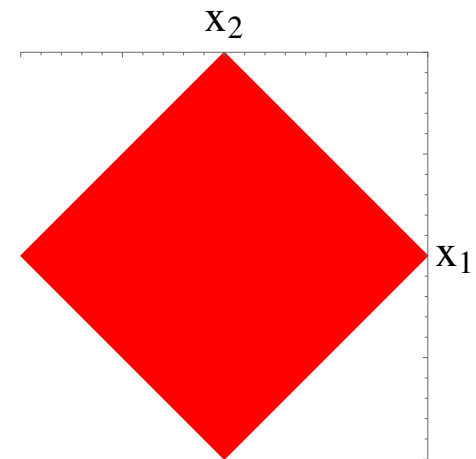
- Smallest ideal **non-extended linear** formulation
 - Generalization of Cayley Embedding of Polytopes
 - Hyperplane arrangements
- Small ideal **non-extended nonlinear** formulations
 - Boundary structure of Cayley Embedding: from polytopes to closed convex sets
- “Formulations” with a **general** integer variables (possibly a **fixed** number)

Ideal Non-Extended Formulations and Hyperplane Arrangements

Embedding Formulation = Ideal non-Extended



P_1



P_2

$$Q(H) := \text{conv} \left(\bigcup_{i=1}^n P_i \times \{h^i\} \right)$$

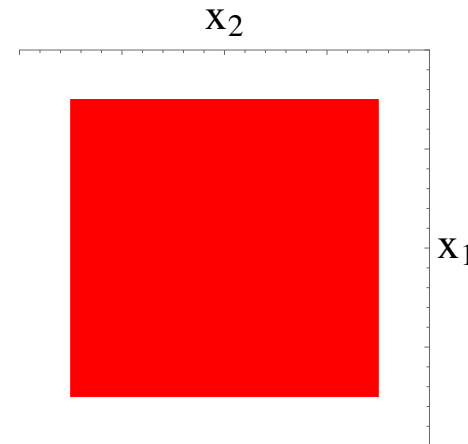
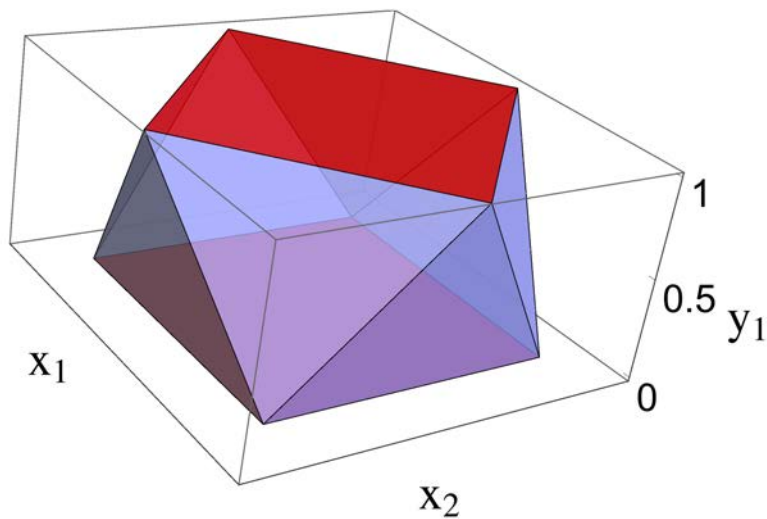
$$(x, y) \in Q \cap (\mathbb{R}^d \times \mathbb{Z}^k) \iff y = h^i \wedge x \in P_i$$

$$\text{ext}(Q) \subseteq \mathbb{R}^d \times \mathbb{Z}^k$$

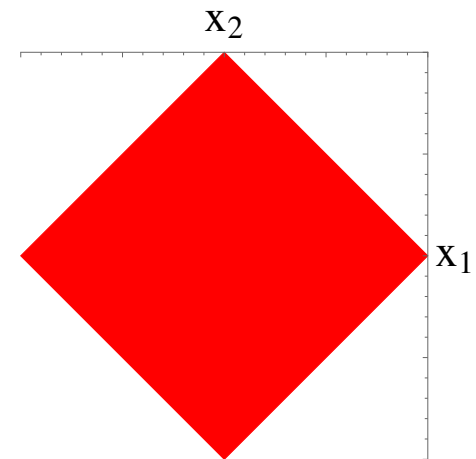
$$H := \{h^i\}_{i=1}^n \subseteq \{0, 1\}^k, \quad h^i \neq h^j$$

$$\text{Cayley} \equiv h^i = e^i, \quad k = n$$

Embedding Formulation = Ideal non-Extended



P_1



P_2

$$Q(H) := \text{conv} \left(\bigcup_{i=1}^n P_i \times \{h^i\} \right)$$

$$(x, y) \in Q \cap (\mathbb{R}^d \times \mathbb{Z}^k) \iff y = h^i \wedge x \in P_i$$

$$\text{ext}(Q) \subseteq \mathbb{R}^d \times \mathbb{Z}^k \quad H := \{h^i\}_{i=1}^n \subseteq \{0, 1\}^k, \quad h^i \neq h^j$$

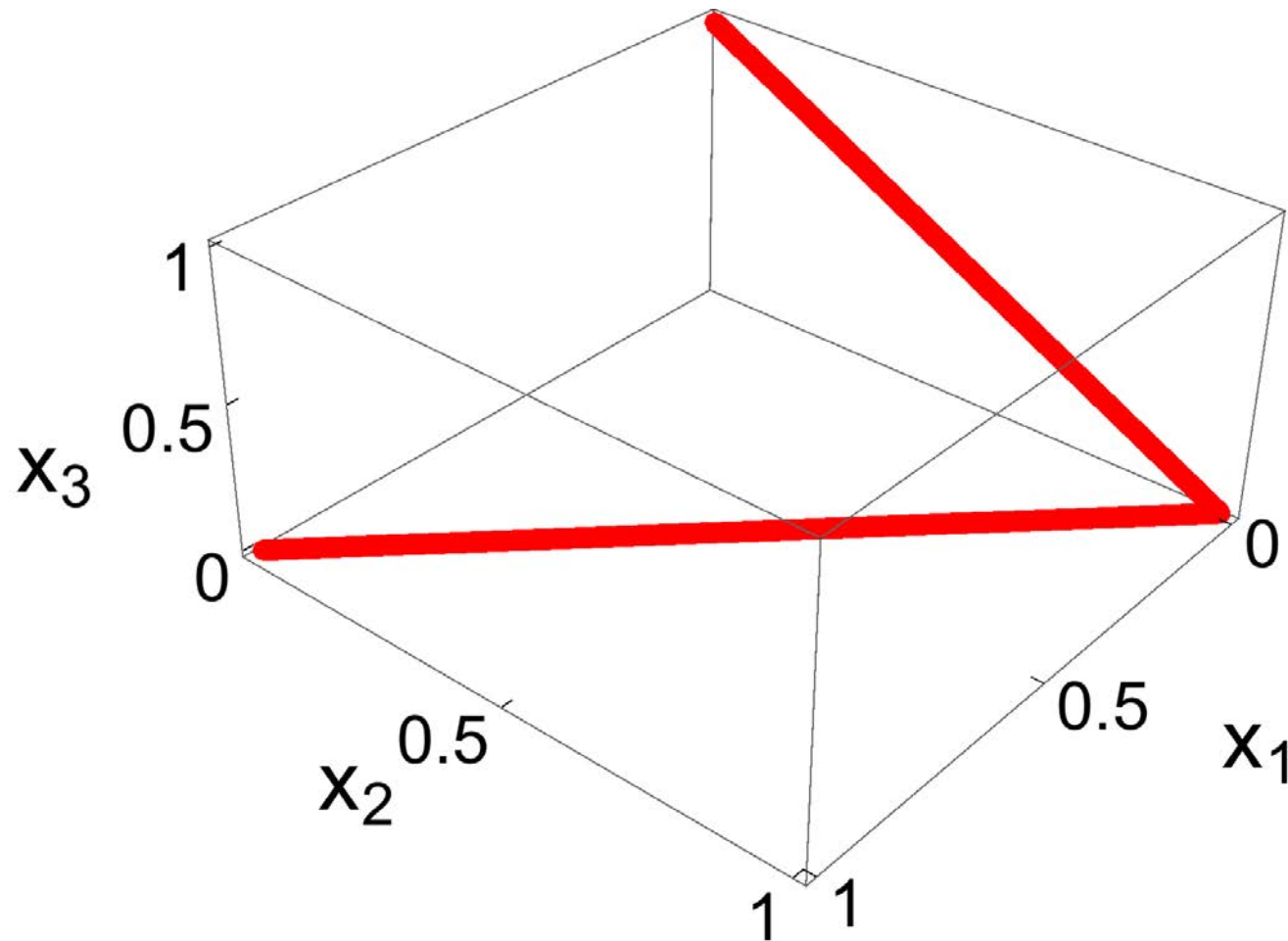
$$\mathcal{P} := \{P_i\}_{i=1}^n \longrightarrow \text{mc}(\mathcal{P}) := \min_H \{\text{size}(Q(H))\}$$

Special Ordered Sets = Simplex Faces = $\mathcal{P} := \{P_i\}_{i=1}^n$

- $\Delta^{d+1} := \left\{ x \in \mathbb{R}_+^{d+1} : \sum_{i=1}^{d+1} x_i = 1 \right\} = \text{conv} \left(\{e^i\}_{i=1}^{d+1} \right)$
 $P_i := \text{conv} \left(\{e^j\}_{j \in T_i} \right) = \left\{ x \in \Delta^{d+1} : \sum_{j \notin T_i} x_j \leq 0 \right\}$
 $T_i \subseteq \{1, \dots, d+1\}$
- $\text{mc}(\mathcal{P}) := \min_H \{ \text{size}(Q(H)) \},$
 $\text{size}(Q(H)) := \# \text{ facets}$
- $\text{mc}_G(\mathcal{P}) := \min_H \{ \text{size}_G(Q(H)) \},$
 $\text{size}_G(Q(H)) := \# \text{ non-bound facets}$

Special Ordered Sets of Type 2 (SOS2) = $\mathcal{P} := \{P_i\}_{i=1}^n$

- $P_i := \text{conv}(\{e^i, e^{i+1}\}) \subseteq \Delta^{n+1}, \quad i \in [n]$



Special Ordered Sets of Type 2 (SOS2) = $\mathcal{P} := \{P_i\}_{i=1}^n$

- $P_i := \text{conv}(\{e^i, e^{i+1}\}) \subseteq \Delta^{n+1}, \quad i \in [n]$

Claim: $\text{mc}_G(\mathcal{P}) = 2 \lceil \log_2 n \rceil,$
 $n + 1 \leq \text{mc}(\mathcal{P}) \leq n + 1 + 2 \lceil \log_2 n \rceil$

- $(x, y) \in Q(H) = \text{conv}\left(\bigcup_{i=1}^n P_i \times \{h^i\}\right)$
 $= \text{conv}\left(\bigcup_{i=1}^n \{e^i, e^{i+1}\} \times \{h^i\}\right)$

- $a \cdot x \leq b \cdot y \quad a_{i+1} \leq \min\{b \cdot h^i, b \cdot h^{i+1}\}$

$$b \in L(H) := \text{aff}(H) - h^1 \quad b \cdot \underbrace{(h^{i+1} - h^i)} = 0$$

Embedding Formulation for SOS2: Part 1

- From encodings (H) to hyperplanes:

$$\{h^i\}_{i=1}^n$$

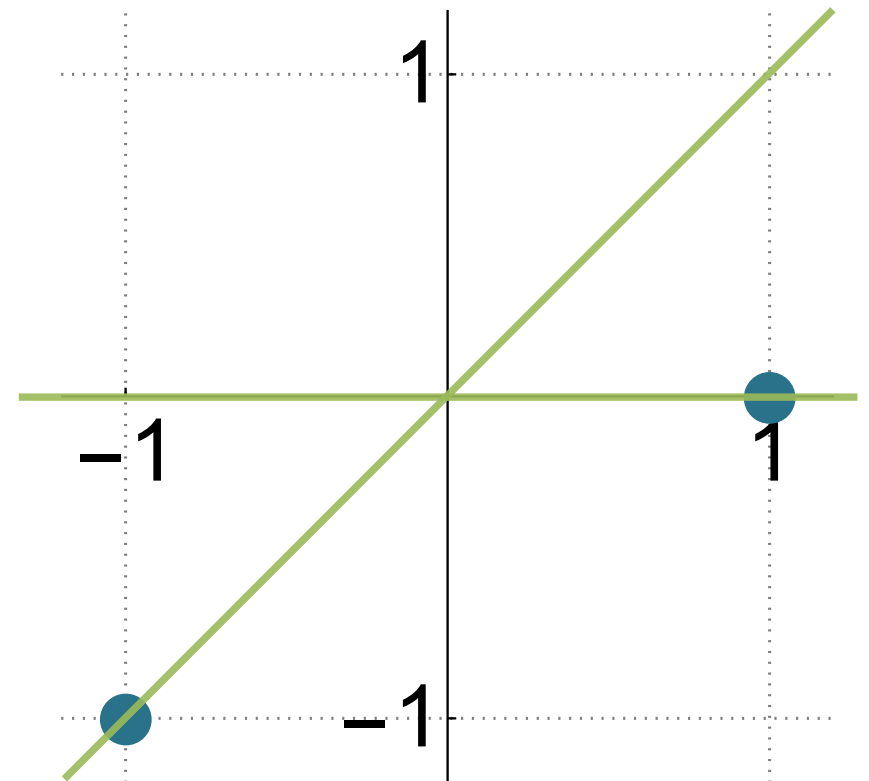
$$h^1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, h^2 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, h^3 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$c^i = h^{i+1} - h^i$$

$$\{c^i\}_{i=1}^{n-1}$$

Hyperplanes spanned by

$$\{b^i \cdot y = 0\}_{j=1}^L$$



Embedding Formulation for SOS2: Part 1

- From encodings (H) to hyperplanes:

$$\{h^i\}_{i=1}^n$$

$$h^1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, h^2 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, h^3 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$c^i = h^{i+1} - h^i$$



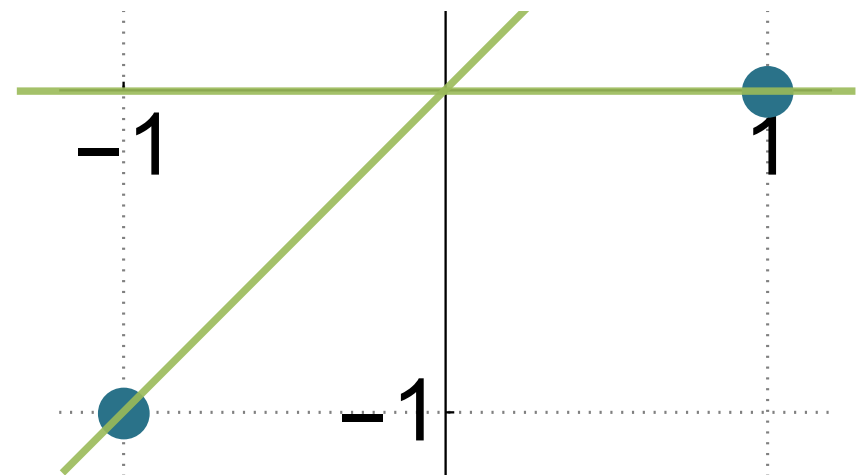
non-bound facets = $2 \times$ # of hyperplanes

$$\cup_{i=1}^n$$

Hyperplanes spanned by



$$\{b^i \cdot y = 0\}_{j=1}^L$$



Embedding Complexity for SOS2

- Lower Bound: $L(H) := \text{aff}(H) - h^1$

$$\text{mc}_G(\mathcal{P}) \geq 2 \times \min \# \text{ of hyperplanes}$$

$$\min \# \text{ of hyperplanes} \geq \dim(L(H))$$

$$\dim(L(H)) \geq \lceil \log_2 n \rceil$$

- Upper Bound: $H = \{0, 1\}^{\lceil \log_2 n \rceil}$

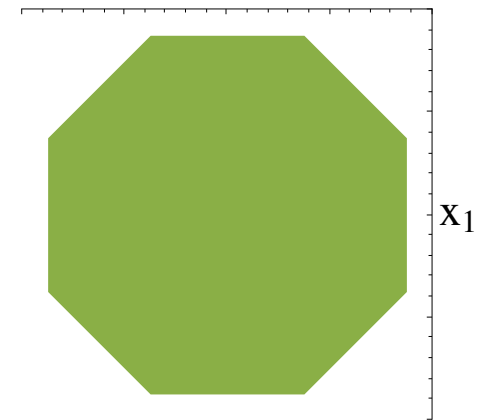
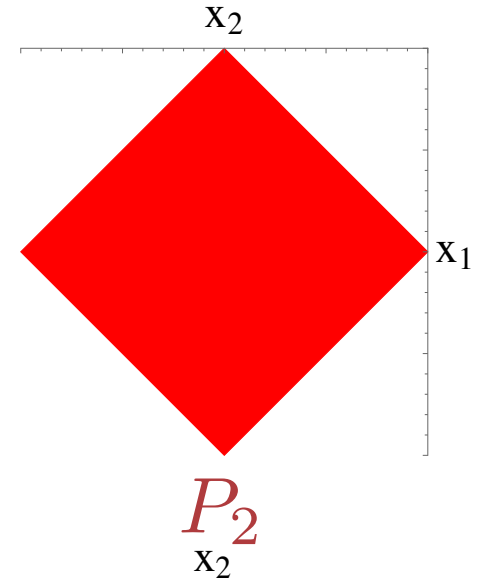
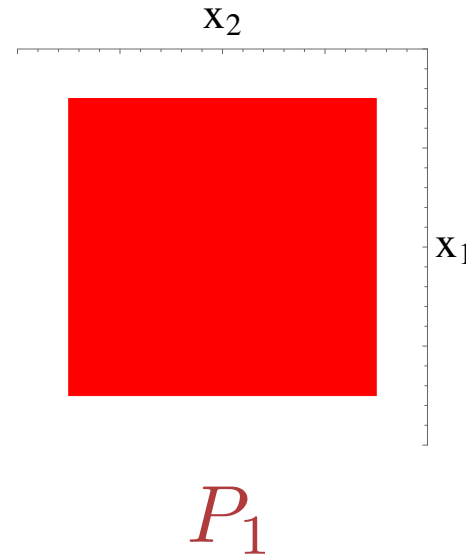
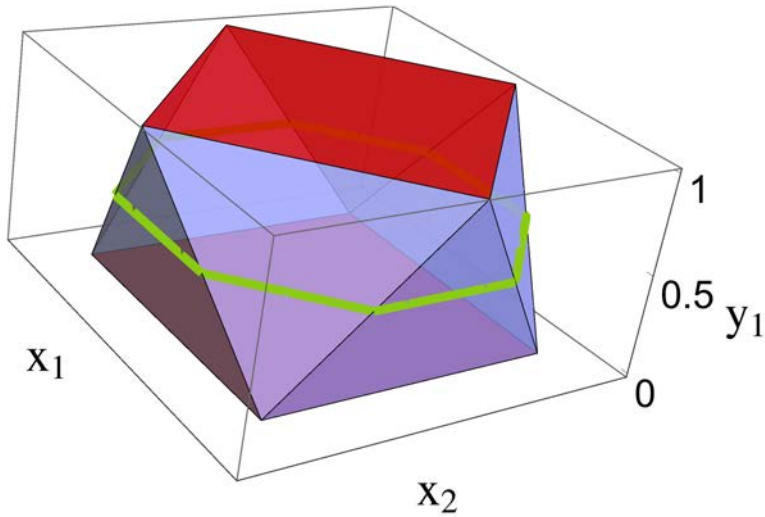
$$\text{– Gray code: } \{h^i - h^{i+1}\}_{i=1}^{n-1} \equiv \{e^i\}_{i=1}^{\lceil \log_2 n \rceil}$$

$$\text{size}_G(Q(H)) = 2 \lceil \log_2 n \rceil$$

$$n + 1 \leq \text{mc}(\mathcal{P}) \leq n + 1 + 2 \lceil \log_2 n \rceil$$

Minkowski Sums and Nonlinear MIP Formulations

Unary Encoding, Minkowski Sum and Cayley Trick



$$Q \cap (\mathbb{R}^2 \times \{0.5\}) \equiv P_1 + P_2 =$$

$$H = \{e^i\}_{i=1}^n$$

$$Q(H) \cap (\mathbb{R}^d \times \{\frac{1}{n} \sum_{i=1}^n e^i\}) \equiv \sum_{i=1}^n P_i$$

Faces of Cayley Embedding

- Two types of facets (or faces):

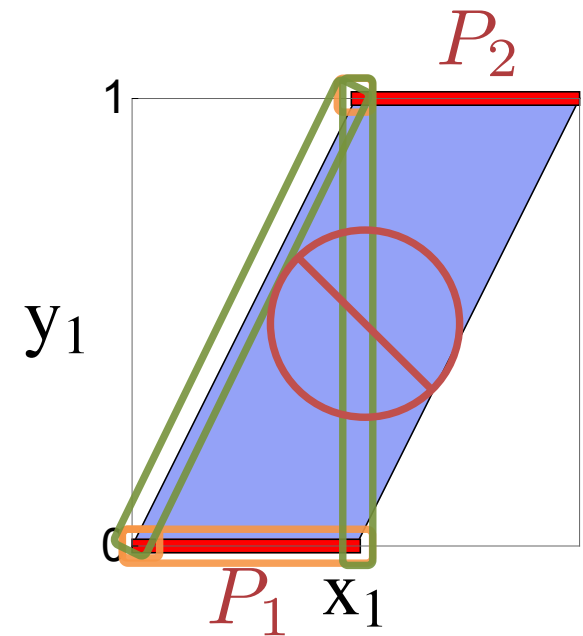
- $P_1 \times \{0\} \equiv y_i \geq 0$

- $\text{conv}((F_1 \times 0) \cup (F_2 \times 1))$

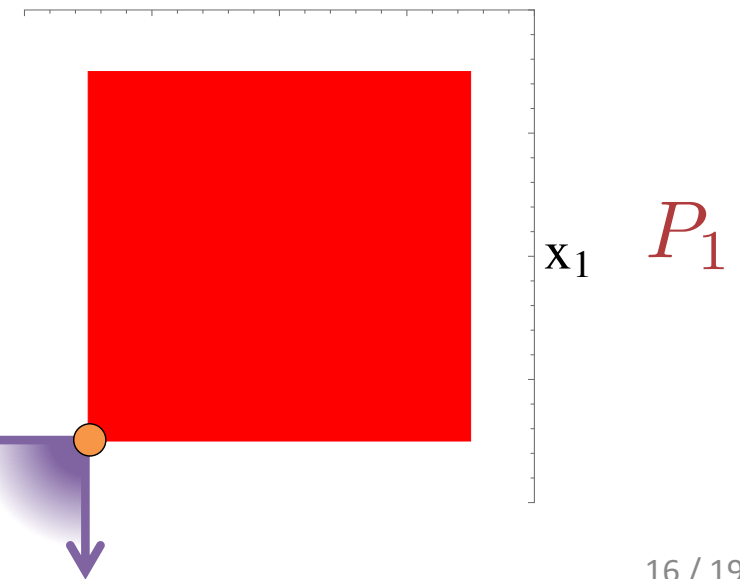
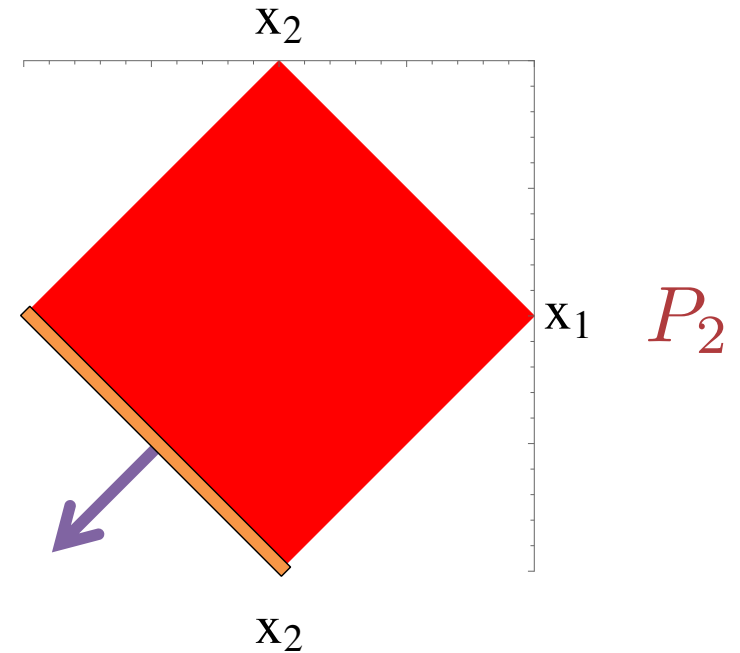
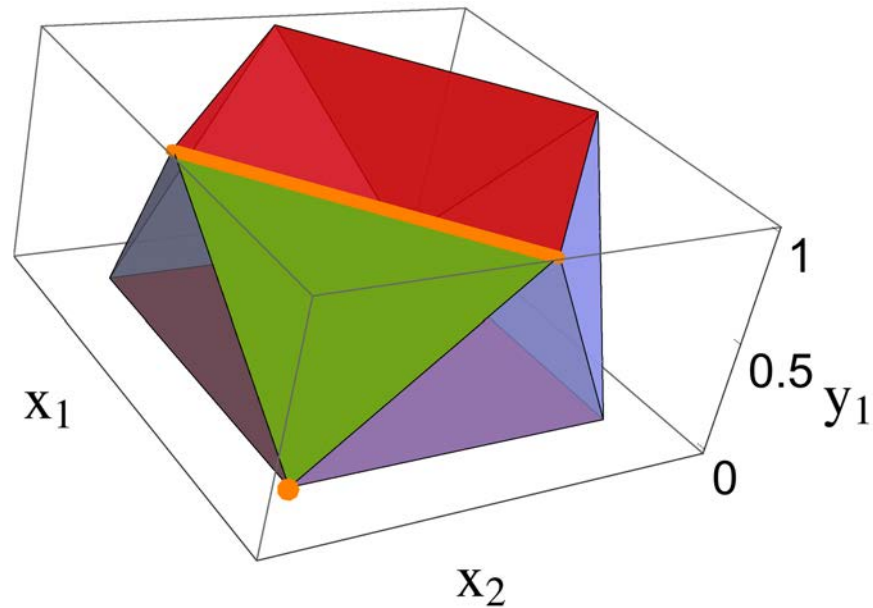
F_i proper face of P_i

- Not all combinations of faces

- Which ones are valid?



Valid Combinations = Common Normals

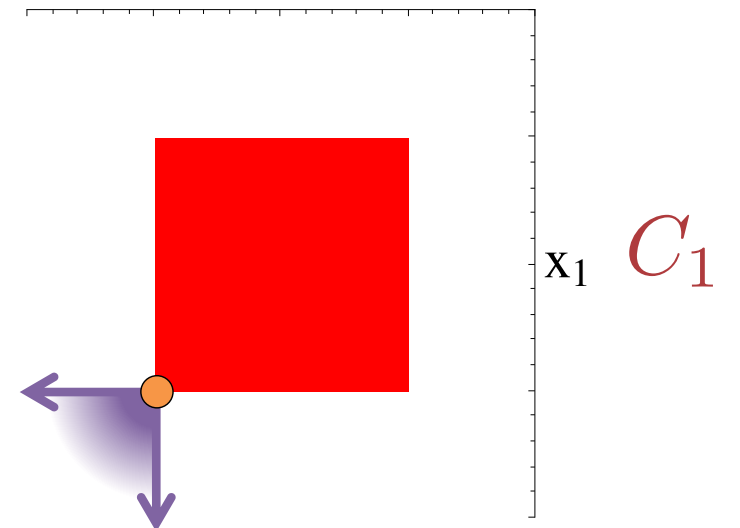
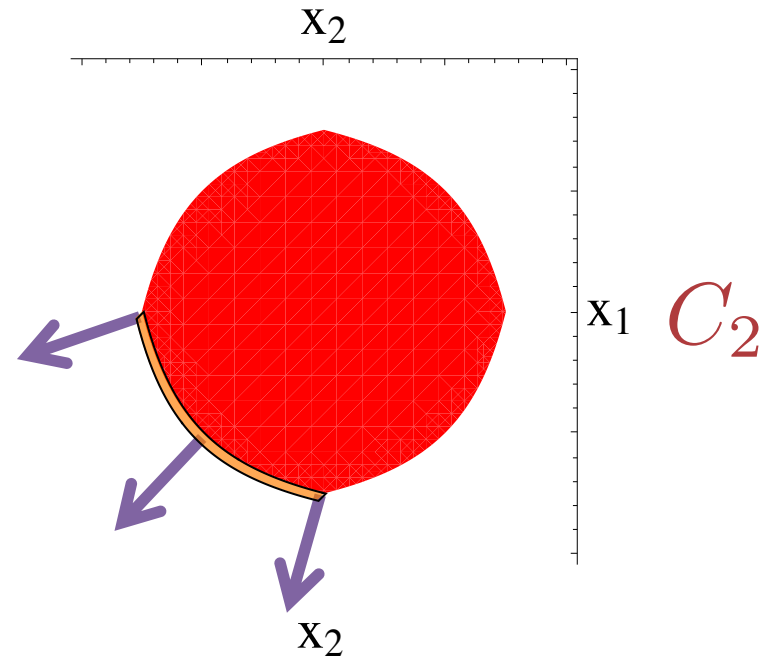
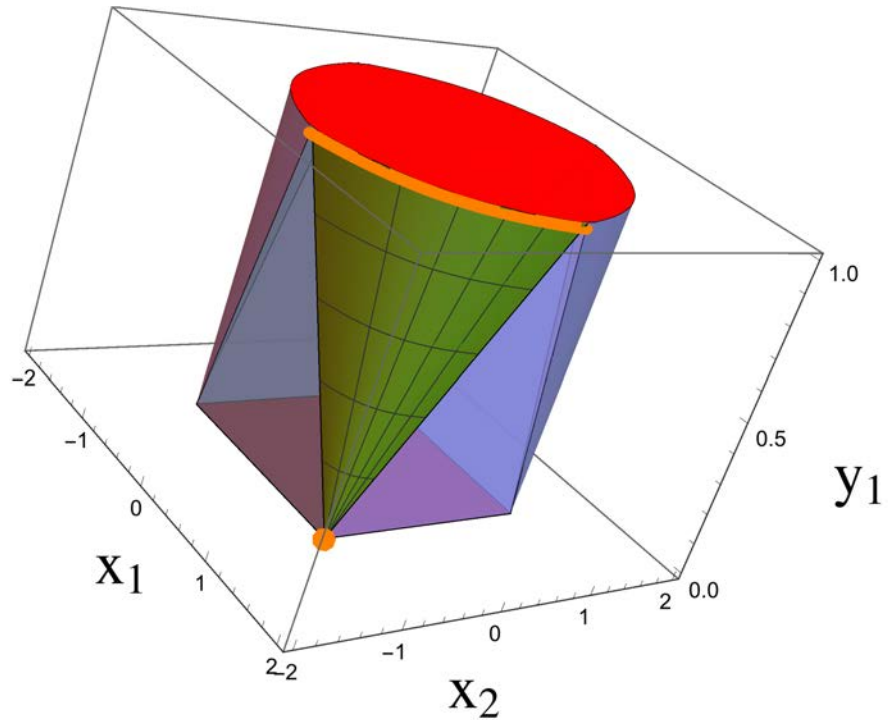


$$N(F_1) \cap N(F_2) \neq \emptyset$$



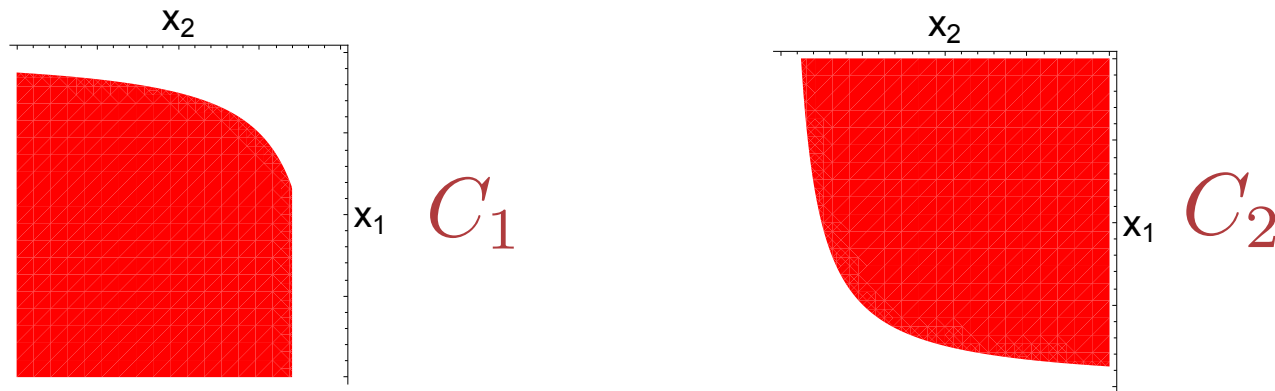
$\text{conv}((F_1 \times 0) \cup (F_2 \times 1))$
is face of $Q(H)$

Characterization Extends to Closed Convex Sets



Small Formulations for Isotone Sets

- Studied by Hijazi et al. '12 and Bonami et al. '15 (n=1, 2):
 - $C_i = \{x \in \mathbb{R}^d : l^i \leq x \leq u^i, f_i(x) \leq 0\}$
- $f_i(x)$ component-wise monotonous (i=1,2 opposite).



- Ideal Formulation

$$y_1 l^1 + y_2 l^2 \leq x \leq y_1 u^1 + y_2 u^2$$

$$f_J^i(x, y) \leq 0$$

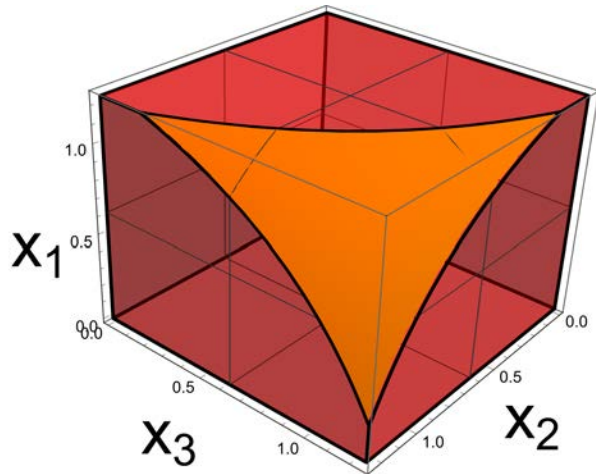
$$\forall J \subseteq [d], i \in [2]$$

$$y_1 + y_2 = 1$$

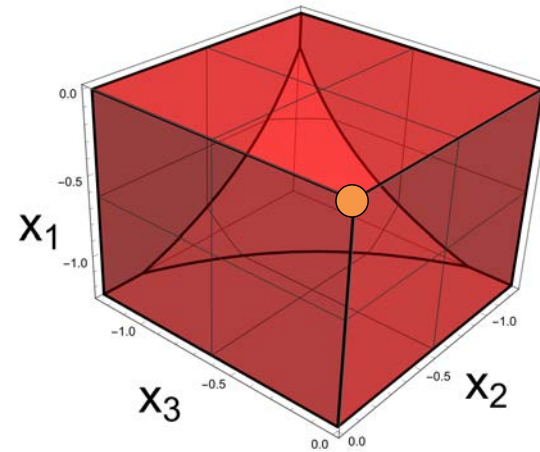
$$y_i \in \{0, 1\}$$

$$i \in [2]$$

Boundary Structure = Redundancy Detection



C_1



C_2

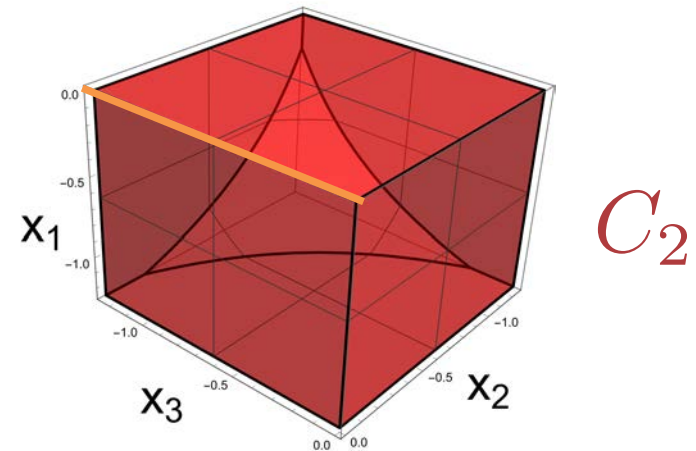
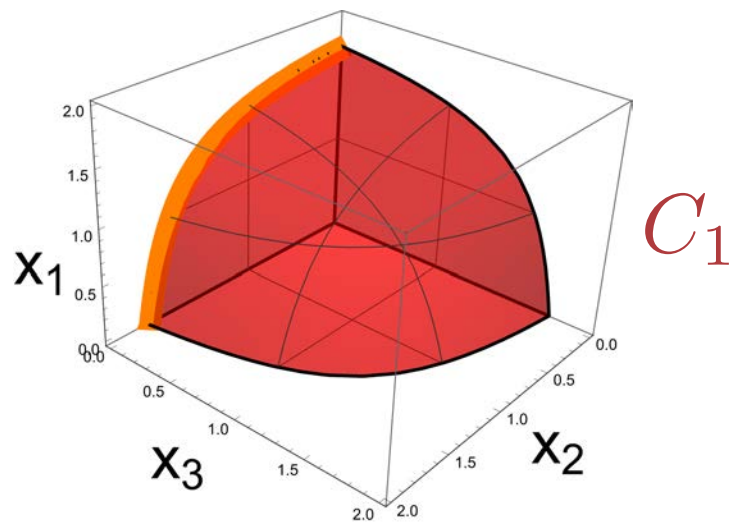
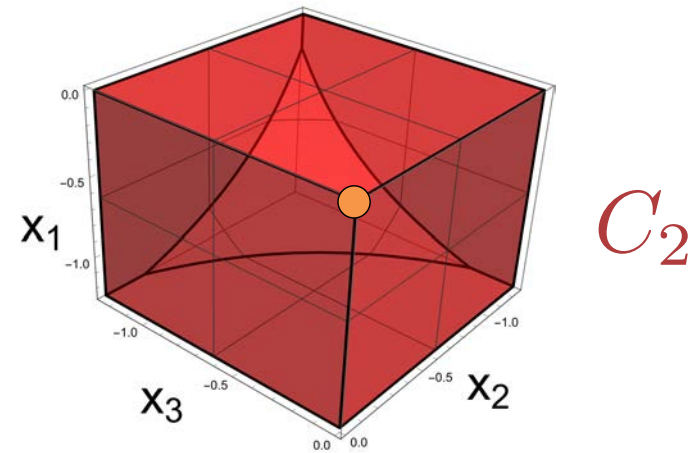
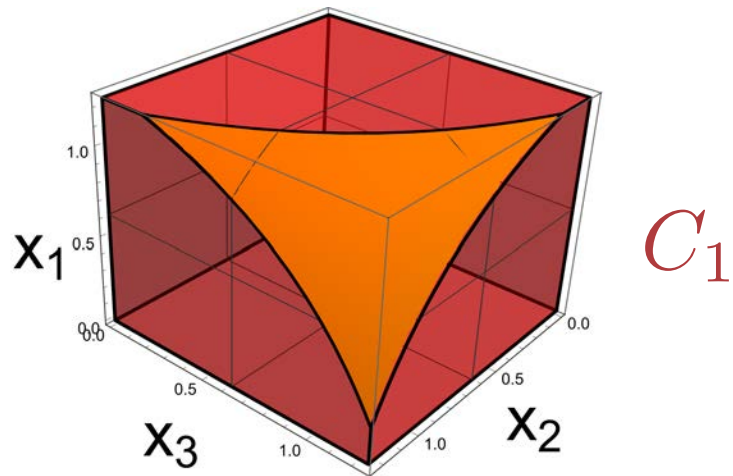
$$y_1 l^1 + y_2 l^2 \leq x \leq y_1 u^1 + y_2 u^2$$

$$f^i(x, y) \leq 0 \quad \forall i \in [2]$$

$$y_1 + y_2 = 1$$

$$y_i \geq \{0, 1\} \quad i \in [2]$$

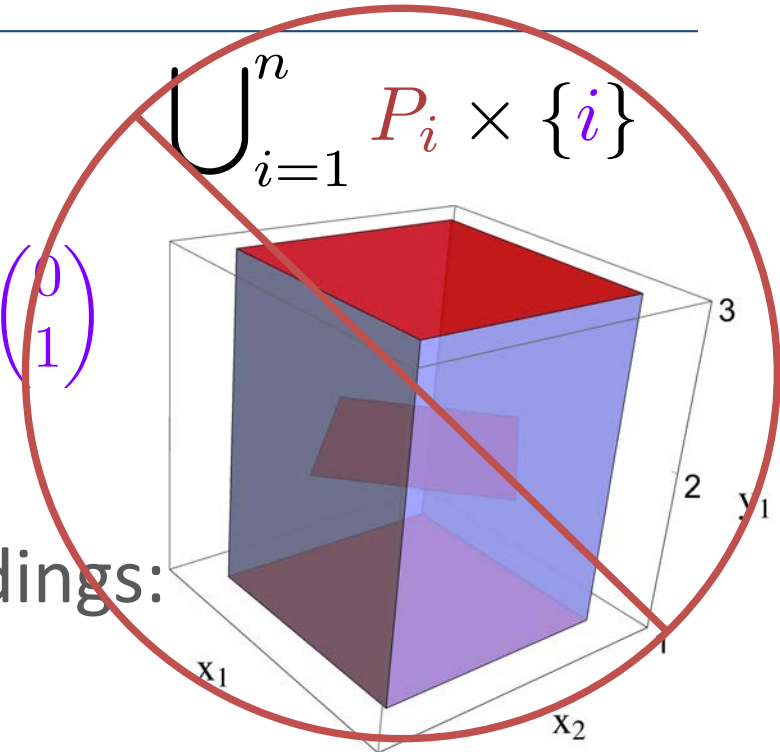
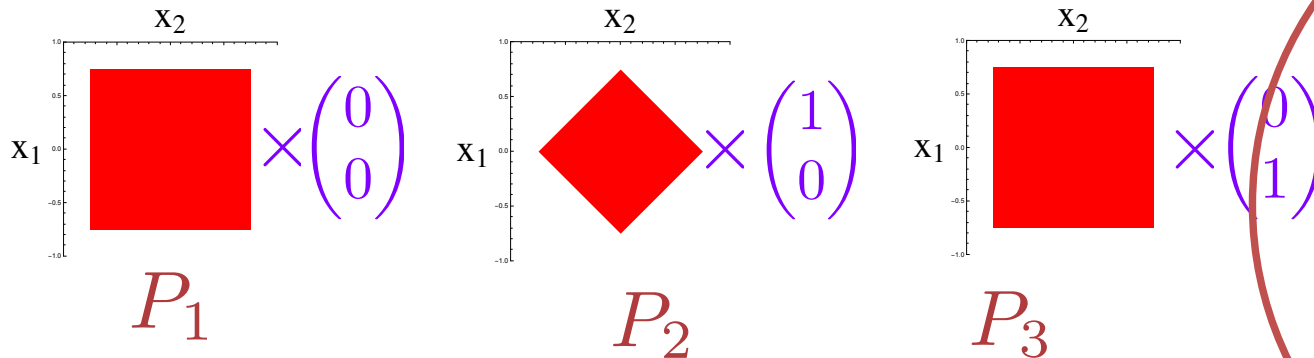
Boundary Structure = Redundancy Detection



“Formulations” With a Fixed Number of General Integer Variables

Alternative Encodings

- “Only” use 0-1 encodings ?



- General integer (rational?) encodings:
 - Points in convex position
 - Recover convex sets by (possibly non-axis aligned) sections
 - Example: Integers in moment curve
 - For SOS2: Hyperplane characterization still works
 - 2-dim moment curve = $2(n-1)$ general inequalities
 - More bounds soon (with Joey Huchette)

Summary

- Embedding Formulations = Systematic procedure for ideal non-extended formulations
 - Encoding can significantly affect size
 - Results beyond SOS2, but many open questions
- Extension to General Convex Sets
 - Can yield practical formulations
 - Not always practical (basic semi-algebraic representability)
- Using General Integer Variables
 - Smaller formulations not likely (in general)
 - General convex MIP representability (w. M. Lubin and I. Zadik):
 - The set of prime numbers is not convex MIP representable