

# A Lifted Linear Programming Branch-and-Bound Algorithm for Mixed Integer Conic Quadratic Programs

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# Outline

- 1 Introduction
- 2 Lifted LP Algorithm
- 3 Computational Results
- 4 Final Remarks

# “Convex” Mixed Integer Non-Linear Programming (MINLP) Problems

$$\begin{aligned}
 z_{\text{MINLP}} &:= \max_{x,y} && cx + dy \\
 \text{s.t.} &&& (x, y) \in \mathcal{C} \subset \mathbb{R}^{n+p} \\
 &&& x \in \mathbb{Z}^n
 \end{aligned}
 \tag{MINLP}$$

- $\mathcal{C}$  is a convex compact set.
- Advanced algorithms and Software:
  - NLP based branch-and-bound algorithms (Borchers and Mitchell, 1994, Gupta and Ravindran, 1985, Leyffer 2001 and Stubbs and Mehrotra, 1999,...)
  - Polyhedral relaxation based algorithms (Duran and Grossmann, 1986, Fletcher and Leyffer, 1994, Geoffrion, 1972, Quesada and Grossmann, 1992, Westerlund and Pettersson, 1995, Westerlund et al., 1994,...)
  - CPLEX 9.0+ (ILOG, 2005), Bonmin (Bonami et al., 2005), FilMINT (Abhishek et al., 2006), . . .

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  - CPLEX 9.0+ (ILOG, 2005), Bonmin (Bonami et al., 2005), FilMINT (Abhishek et al., 2006), . . .
- Polyhedral relaxation algorithms try to exploit the technology for Mixed Integer **Linear** Programming

# Branch-and-Bound Methods

- A branch-and-bound node is defined by  $(l^k, u^k) \in \mathbb{Z}^{2n}$ .
- The problem solved in a branch-and-bound node  $(l^k, u^k)$  is obtained by adding  $l^k \leq x \leq u^k$  to some continuous relaxation of MINLP.
- Example:

$$z_{\text{NLP}}(l^k, u^k) := \max_{x, y} cx + dy$$

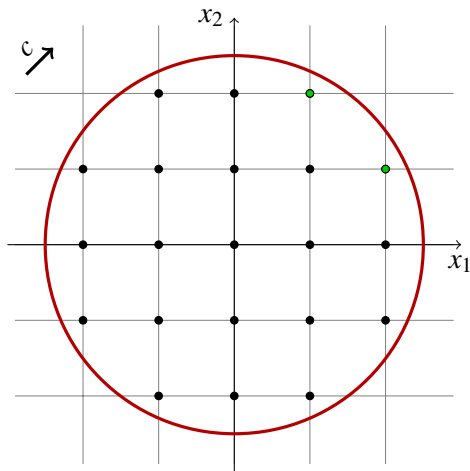
*s.t.*

$$(x, y) \in \mathcal{C} \subset \mathbb{R}^{n+p} \quad (\text{NLP}(l^k, u^k))$$

$$x \geq l^k$$

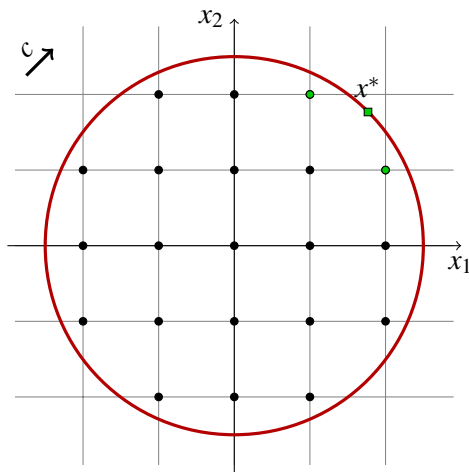
$$x \leq u^k$$

# NLP Based Branch-and-Bound Algorithms



$$\begin{aligned} \max_x \quad & x_1 + x_2 \\ & x \in \mathcal{B}^2(2.5) \quad (\text{MINLP}) \\ & x \in \mathbb{Z}^2 \end{aligned}$$

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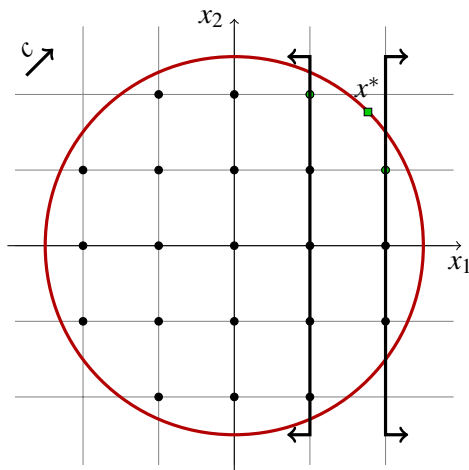


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NLP( $(-\infty, -\infty)^\top, (\infty, \infty)^\top$ ):

- $x_1^* = x_2^* \approx 1.77 \notin \mathbb{Z}$ .
- Branch:  $x_1 \leq 1 \vee x_1 \geq 2$ .

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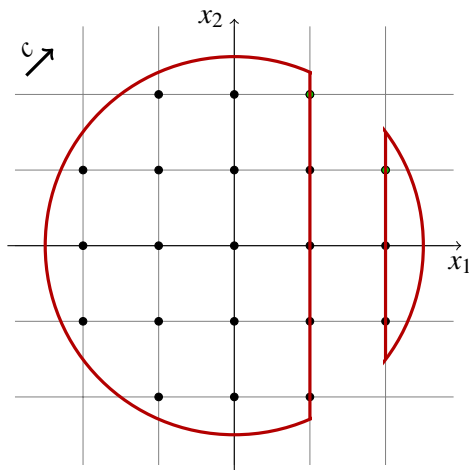
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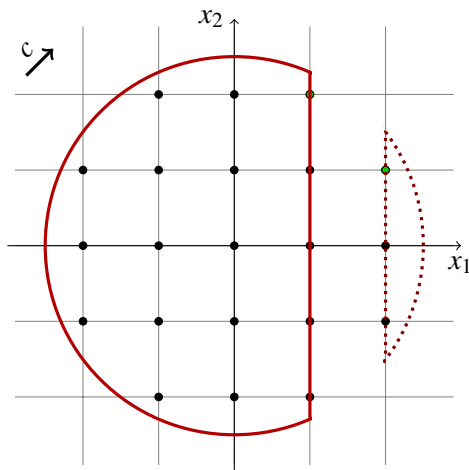
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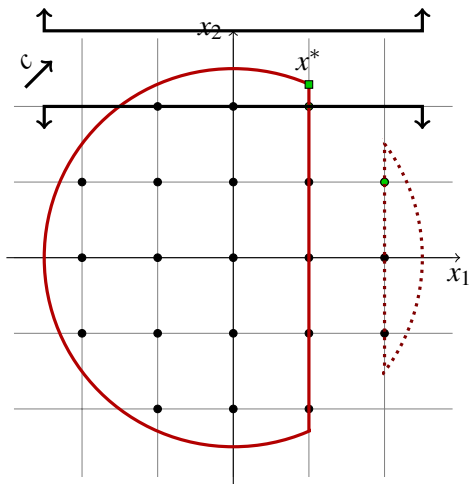
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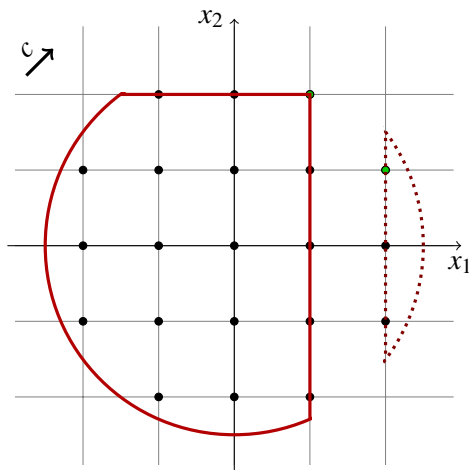
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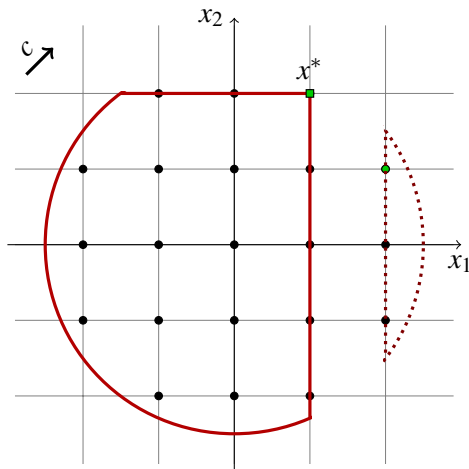
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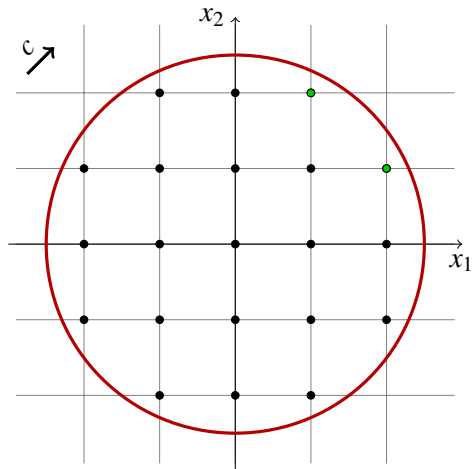
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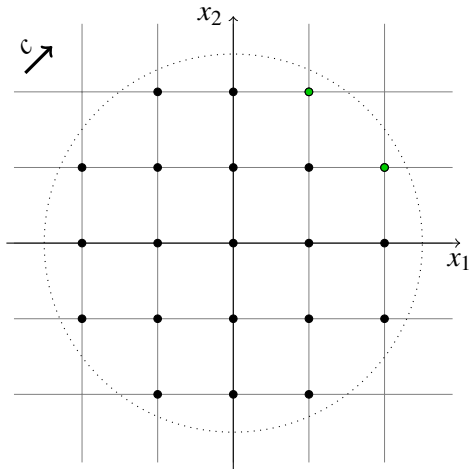


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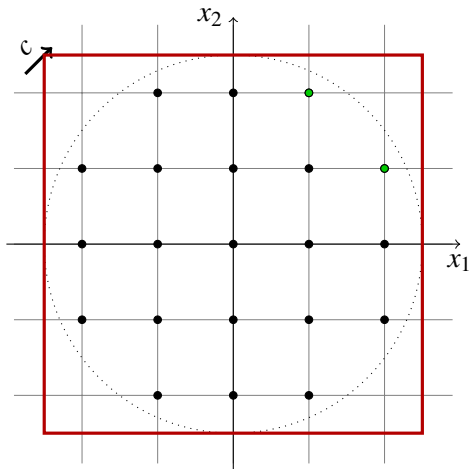
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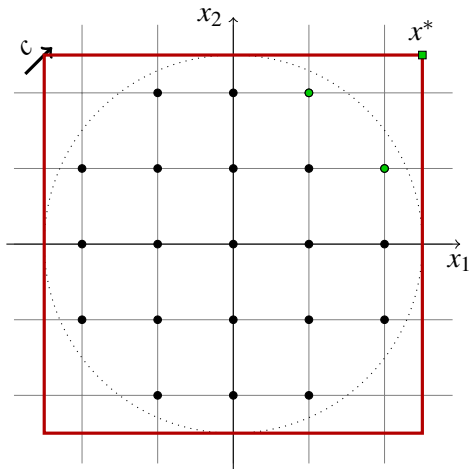
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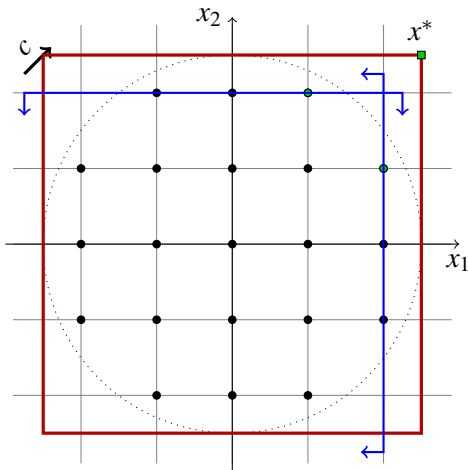
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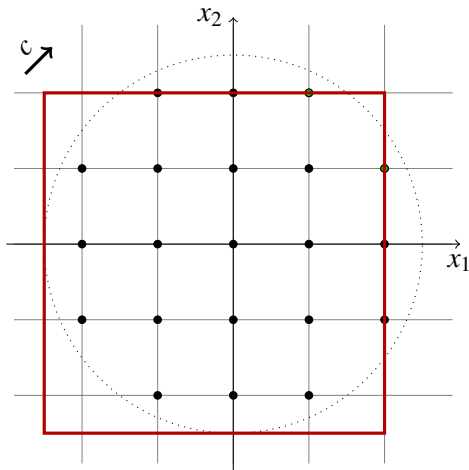
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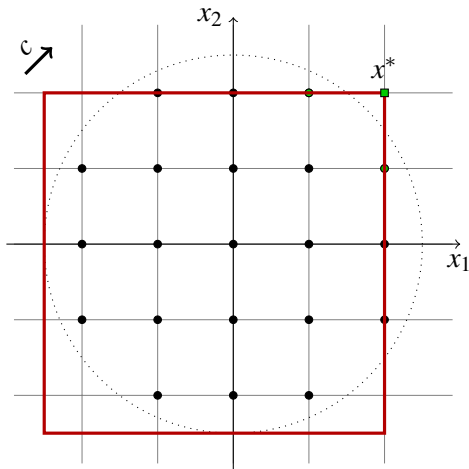
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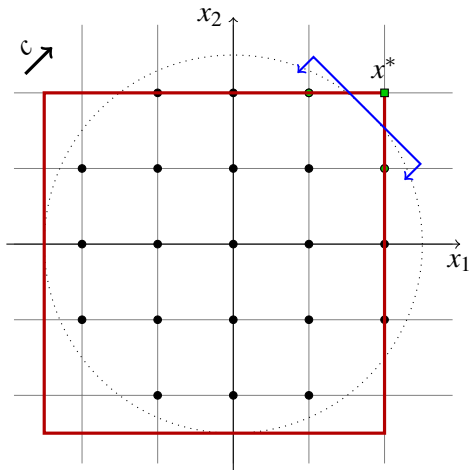
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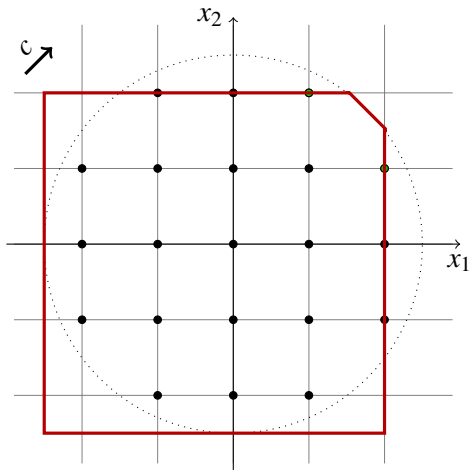
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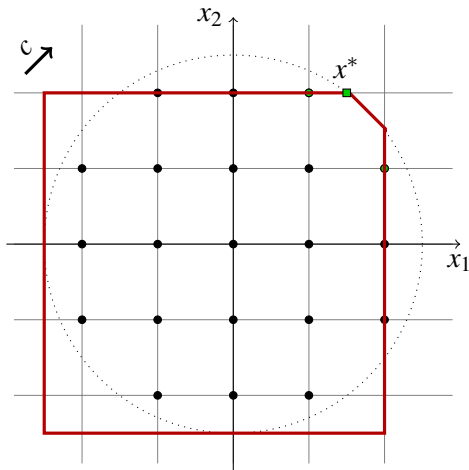
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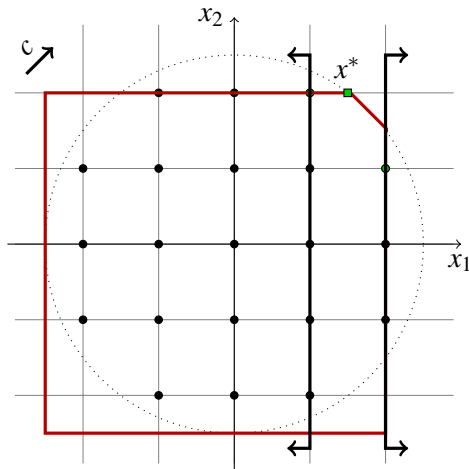
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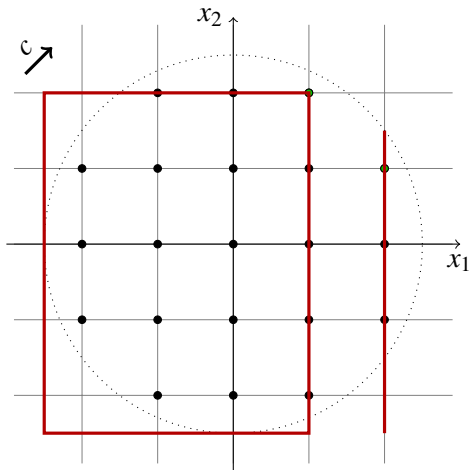
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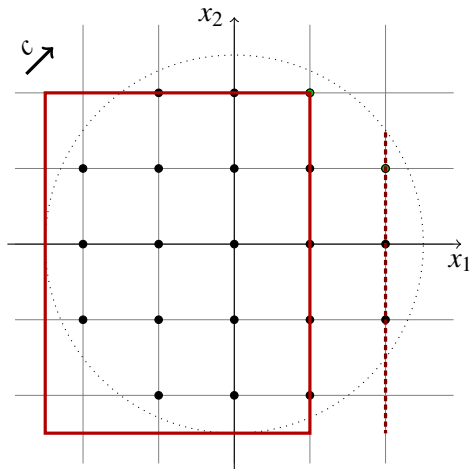
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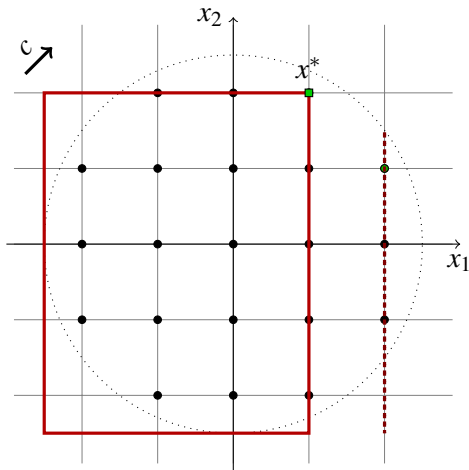
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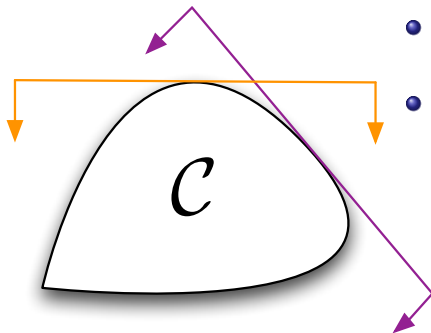
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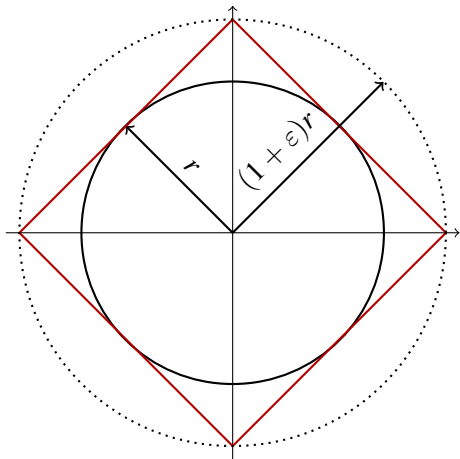
# Polyheral Relaxation Based Algorithms



- Approximate convex sets using gradient cuts (tangent, benders).
- Cuts are in the original space.
- Usually only a few cuts are necessary.
- Sometimes convergence of cutting plane procedure is bad (e.g. Quadratic constraints).
  - Solution: Use a polyhedral approximation of the whole set.

# Polyheral Relaxation of Convex Sets

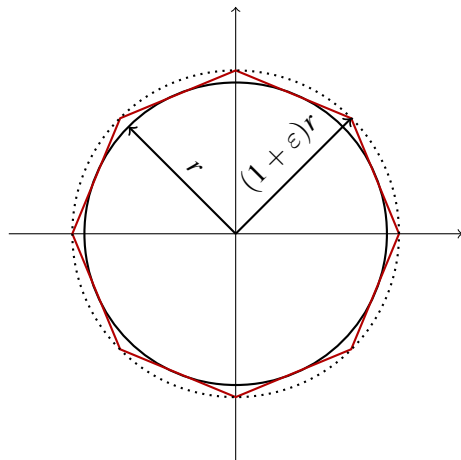
$$\mathcal{C} = \mathcal{B}^d(r), \quad d = 2, \quad \varepsilon = 0.41$$



- It is known that at least  $\exp(d/(2(1+\varepsilon))^2)$  facets are needed in the original space.
- Ben-Tal and Nemirovski (2001) approximate  $\mathcal{B}^d(r)$  as the **projection** of a polyhedron with  $O(d \log(1/\varepsilon))$  variables and constraints.
- Glineur (2000) refined the approximation and showed that it is algorithmically and computationally “impractical” for (pure continuous) conic quadratic optimization.

# Polyheral Relaxation of Convex Sets

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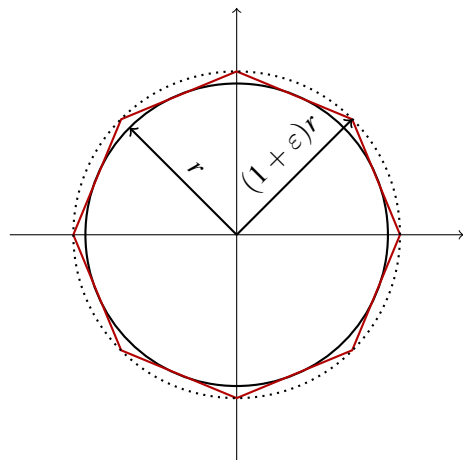
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# Using Ben-Tal Nemirovski Approximation to Exploit Mixed Integer **Linear** Programming Solver Technology

- **Lifted** linear programming relaxation: Polyhedron  $\mathcal{P} \subset \mathbb{R}^{n+p+q}$  such that

$$\mathcal{C} \subset \{(x, y) \in \mathbb{R}^{n+p} : \exists v \in \mathbb{R}^q \text{ s.t. } (x, y, v) \in \mathcal{P}\} \approx \mathcal{C}$$

- Use a state of the art MILP solver to solve

$$\begin{aligned} \max_{x, y, v} \quad & cx + dy \\ \text{s.t.} \quad & (x, y, v) \in \mathcal{P} \\ & x \in \mathbb{Z}^n \end{aligned} \quad (\text{MILP})$$

- Problem: Obtained solution might not even be feasible for MINLP
- Solution: Modify Solve of MILP

# Idea: Simulate NLP Branch-and-Bound

- Problem solved in NLP B&B node  $(l^k, u^k) \in \mathbb{Z}^{2n}$  is:

$$\begin{aligned} z_{\text{NLP}}(l^k, u^k) &:= \max_{x, y} cx + dy \\ \text{s.t.} \quad &(x, y) \in \mathcal{C} \subset \mathbb{R}^{n+p} \quad (\text{NLP}(l^k, u^k)) \\ &l^k \leq x \leq u^k \end{aligned}$$

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- Advantages of second subproblem:
  - Algorithmic Advantage: Simplex has warm starts.
  - Computational Advantage: Use MILP solver's technology.

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- Issues:

- 1 Integer feasible solutions may be infeasible for  $\mathcal{C}$ .
- 2 Need to be careful when fathoming by integrality.

# First Issue: Correcting Integer Feasible Solutions

- Let  $(x^*, y^*, v^*) \in \mathcal{P}$  such that  $x^* \in \mathbb{Z}^n$ , but  $(x^*, y^*) \notin \mathcal{C}$ .
- We reject  $(x^*, y^*, v^*)$  and try to correct it using:

$$z_{\text{NLP}(x^*)} := \max_y \quad cx^* + dy$$

*s.t.*

$$(x^*, y) \in \mathcal{C} \subset \mathbb{R}^{n+p}. \quad (\text{NLP}(x^*))$$

- This can be done for solutions found by heuristics, at integer feasible nodes, etc.

## Second Issue: Correct Fathoming by Integrality

- Suppose that for a node  $(l^k, u^k)$  with  $l^k \neq u^k$  we have that the solution  $(x^*, y^*, v^*)$  of  $\text{LP}(l^k, u^k)$  is such that  $x^* \in \mathbb{Z}^n$
- If  $(x^*, y^*) \in \mathcal{C}$  then  $(x^*, y^*)$  is also the optimal for  $\text{NLP}(l^k, u^k)$  and we can fathom by integrality.
- If  $(x^*, y^*) \notin \mathcal{C}$  it is not sufficient to solve  $\text{NLP}(x^*)$ :
  - Problem: Corrected solution is not necessarily optimal for  $\text{NLP}(l^k, u^k)$ .
  - Solution: Solve  $\text{NLP}(l^k, u^k)$  and process node according to its solution.

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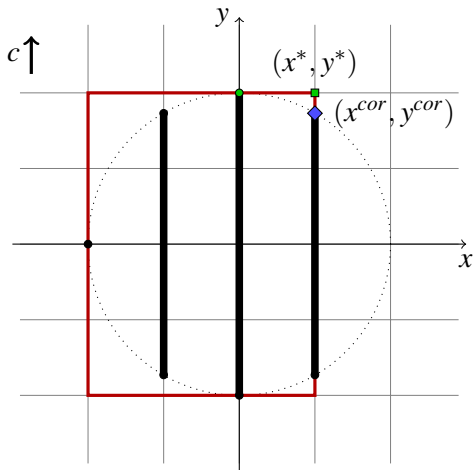
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# Correcting Integer Feasible Solutions is Not Enough



$$\max_{x,y} y$$

$$(x, y) \in \mathcal{B}^2(2) \quad (\text{MINLP})$$

$$x \in \mathbb{Z}$$

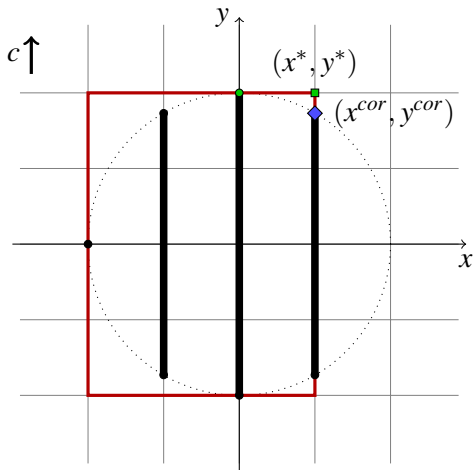
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$$(x, y) \in [-2, 2]^2 \quad (\text{LP})$$

LP( $-\infty, 1$ ):

- $x^* = 1, y^* = 2,$   
 $(x, y) \notin \mathcal{B}^2(2).$
- $\text{NLP}(x^*) \rightarrow (x^{\text{cor}}, y^{\text{cor}}).$
- If we fathom we loose optimum (0, 2)!

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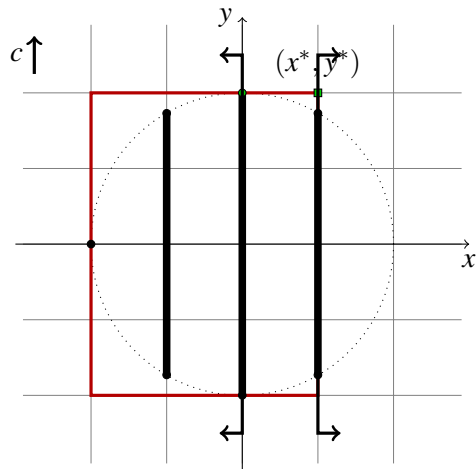
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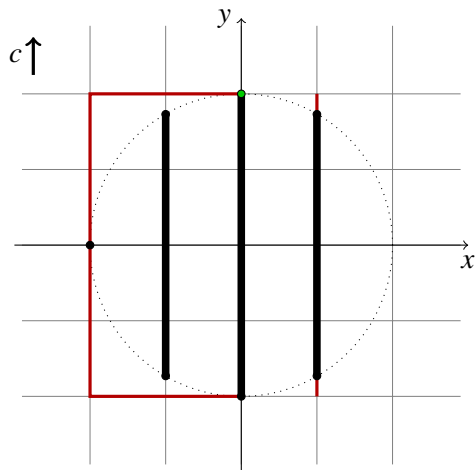
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$$(x, y) \in [-2, 2]^2 \quad (\text{LP})$$

Solution 1:

- Branch:  $x \leq 0 \vee x \geq 1$ .
- Solve LP $(-\infty, 0)$ .
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# Correcting Integer Feasible Solutions is Not Enough



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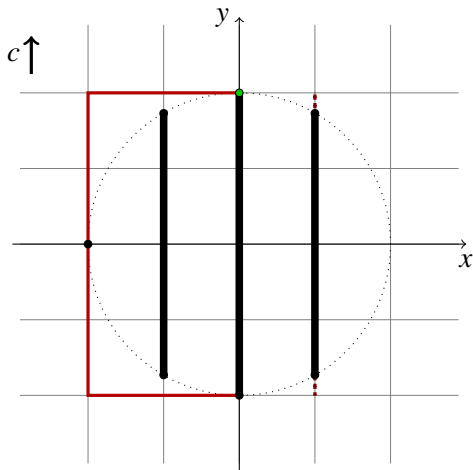
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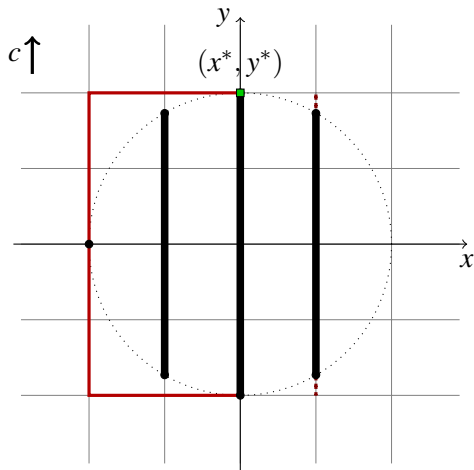
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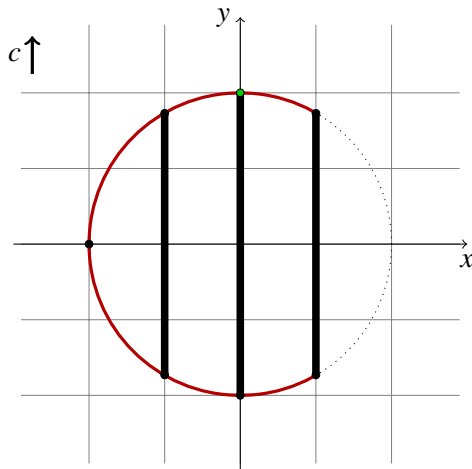
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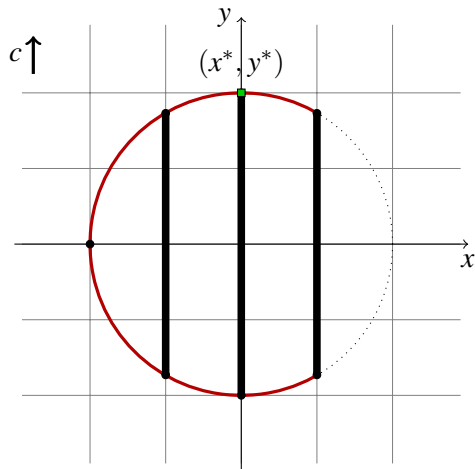
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Solution 2:

- Solve  $\text{NLP}(-\infty, 1)$ .
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# Correcting Integer Feasible Solutions is Not Enough



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Solution 2:

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- We get optimum  $(0, 2)$ .

# Computational Experiments

- Implementation of Lifted LP B&B Algorithm (  $LP(\varepsilon)$ -BB ):
  - Using Ben-Tal Nemirovski relaxation from Glineur (2000).
  - Implemented by modifying CPLEX 10's MILP solver using branch, incumbent and heuristic callbacks.
  - $\varepsilon = 0.01$  was selected after calibration experiments.
- Portfolio optimization problems with cardinality constraints (Ceria and Stubbs, 2006; Lobo et al., 1998, 2007):
  - 3 types, all restricting investment in at most 10 stocks.
  - Random selection from S&P 500.
  - 100 instances for  $n \in \{20, 30, 40, 50\}$ , 10 for  $n \in \{100, 200\}$ .
- Computer and solvers:
  - Dual 2.4GHz Xeon Linux workstation with 2GB of RAM.
  - $LP(\varepsilon)$ -BB v/s CPLEX 10's MIQCP solver and Bonmin's I-BB, I-QG and I-Hyb.

# Problem 1: Classical

$$\max_{x,y} \quad \bar{a}y$$

*s.t.*

$$\|Q^{1/2}y\|_2 \leq \sigma$$

$$\sum_{j=1}^n y_j = 1$$

$$y_j \leq x_j \quad \forall j \in \{1, \dots, n\}$$

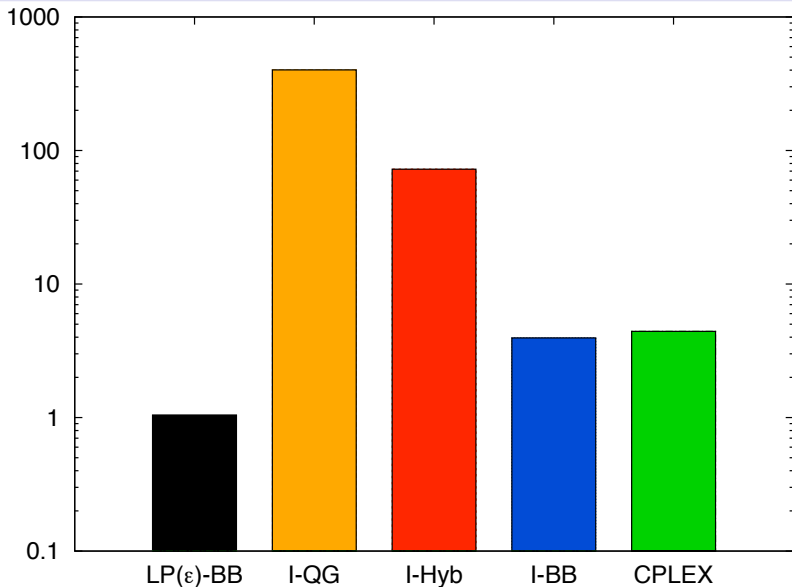
$$\sum_{j=1}^n x_j \leq 10$$

$$x \in \{0, 1\}^n$$

$$y \in \mathbb{R}_+^n$$

- $y$  fraction of the portfolio invested in each of  $n$  assets.
- $\bar{a}$  expected returns of assets.
- $Q^{1/2}$  positive semidefinite square root of the covariance matrix  $Q$  of returns.
- Hold at most 10 assets.

# Average of Solve Times [s] for $n \in \{20, 30\}$



# Total Number of Nodes and Calls to Relaxations for Small Instances

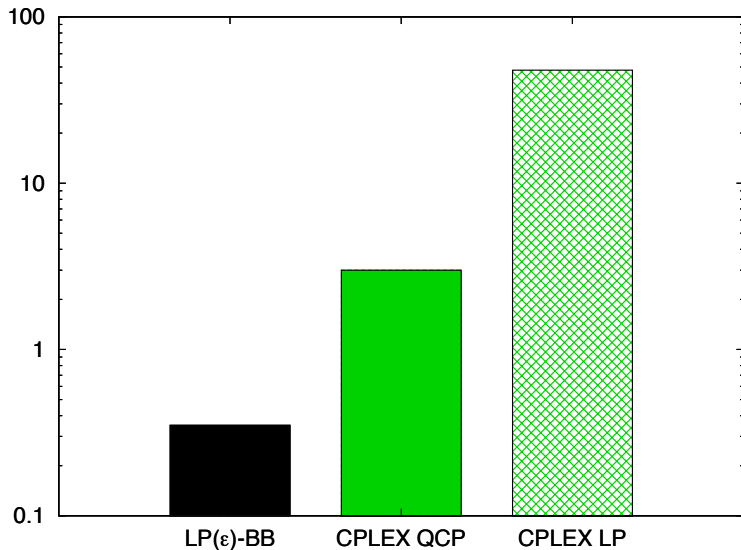
I-QG (B&B nodes)	3,580,051
I-Hyb (B&B nodes)	328,316
I-BB (B&B nodes)	68,915
CPLEX (B&B nodes)	85,957
LP( $\varepsilon$ )-BB (B&B nodes)	57,933

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CPLEX (B&B nodes)	85,957
LP( $\varepsilon$ )-BB (B&B nodes)	57,933
NLP( $l^k, u^k$ ) ( LP( $\varepsilon$ )-BB calls )	2,305
NLP( $x^*$ ) ( LP( $\varepsilon$ )-BB calls )	7,810



# Avg. of Solve Times [s] for $n \in \{20, 30\}$ (CPLEX v11)



# Final Remarks

- Polyhedral relaxation algorithm for “convex” MINLP:
  - Based on a **lifted** polyhedral relaxation.
  - “Does not update the relaxation”.
- Algorithm for the conic quadratic case:
  - Characteristics:
    - Based on a lifted polyhedral relaxation by Ben-Tal and Nemirovski.
    - Implemented by modifying CPLEX MILP solver.
  - Advantages:
    - Can outperform other methods for portfolio optimization problems.
    - Shows that Ben-Tal and Nemirovski approximation can be computationally “practical”.

# Problem 1: Classical

$$\max_{x,y} \quad \bar{a}y$$

s.t.

$$\|Q^{1/2}y\|_2 \leq \sigma$$

$$\sum_{j=1}^n y_j = 1$$

$$y_j \leq x_j \quad \forall j \in \{1, \dots, n\}$$

$$\sum_{j=1}^n x_j \leq K$$

$$x \in \{0, 1\}^n$$

$$y \in \mathbb{R}_+^n$$

- $y$  fraction of the portfolio invested in each of  $n$  assets.
- $\bar{a}$  expected returns of assets.
- $Q^{1/2}$  positive semidefinite square root of the covariance matrix  $Q$  of returns.
- $K$  maximum number of assets to hold.

## Problem 2 : Shortfall

$$\max_{x,y} \quad \bar{a}y$$

s.t.

$$\|Q^{1/2}y\|_2 \leq \sigma$$

$$\sum_{j=1}^n y_j = 1$$

$$y_j \leq x_j \quad \forall j \in \{1, \dots, n\}$$

$$\sum_{j=1}^n x_j \leq K$$

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# Problem 2 : Shortfall

$$\max_{x,y} \quad \bar{a}y$$

s.t.

$$\|Q^{1/2}y\|_2 \leq \frac{\bar{a}y - W_i^{low}}{\Phi^{-1}(\eta_i)} \quad i \in \{1, 2\}$$

$$\sum_{j=1}^n y_j = 1$$

$$y_j \leq x_j \quad \forall j \in \{1, \dots, n\}$$

$$\sum_{j=1}^n x_j \leq K$$

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- $Q^{1/2}$  positive semidefinite square root of the covariance matrix  $Q$  of returns.
- $K$  maximum number of assets to hold.
- **Approximation of**  
 $\text{Prob}(\bar{a}y \geq W_i^{low}) \geq \eta_i$

# Problem 3 : Robust

$$\max_{x,y,r} \quad r$$

s.t.

$$\|Q^{1/2}y\|_2 \leq \sigma$$

$$\alpha\|R^{1/2}y\|_2 \leq \bar{a}y - r$$

$$\sum_{j=1}^n y_j = 1$$

$$y_j \leq x_j \quad \forall j \in \{1, \dots, n\}$$

$$\sum_{j=1}^n x_j \leq K$$

$$x \in \{0, 1\}^n$$

$$y \in \mathbb{R}_+^n$$

- $y$  fraction of the portfolio invested in each of  $n$  assets.
- $\bar{a}$  expected returns of assets.
- $Q^{1/2}$  positive semidefinite square root of the covariance matrix  $Q$  of returns.
- $K$  maximum number of assets to hold.
- **Robust version from uncertainty in  $\bar{a}$ .**

# Instance Data

- Maximum number of stocks  $K = 10$ .
- Maximum risk  $\sigma = 0.2$ .
- Shortfall constraints:  $\eta_1 = 80\%$ ,  $W_1^{low} = 0.9$ ,  $\eta_2 = 97\%$ ,  $W_2^{low} = 0.7$  (Lobo et al., 1998, 2007).
- Data generation for Classical and Shortfall from S&P 500 data following Lobo et al. (1998), (2007).
- Data generation for Robust from S&P 500 data following Ceria and Stubbs (2006).
- Riskless asset included for Shortfall.
- Random selection of  $n$  stocks out of 462.
- 100 instances for  $n \in \{20, 30, 40, 50\}$ , 10 for  $n \in \{100, 200\}$ .

# Branch-and-Bound Main Loop

- 1 Set global lower bound  $LB := -\infty$ .
- 2 Set  $l_i^0 := -\infty, u_i^0 := +\infty$  for all  $i \in \{1, \dots, n\}$ .
- 3 Set node list  $\mathcal{H} := \{(l^0, u^0)\}$ .
- 4 **while**  $\mathcal{H} \neq \emptyset$  **do**
- 5     |     Select and **remove** a node  $(l^k, u^k) \in \mathcal{H}$ .
- 6     |     ProcessNode( $l^k, u^k$ ).
- 7 **end**



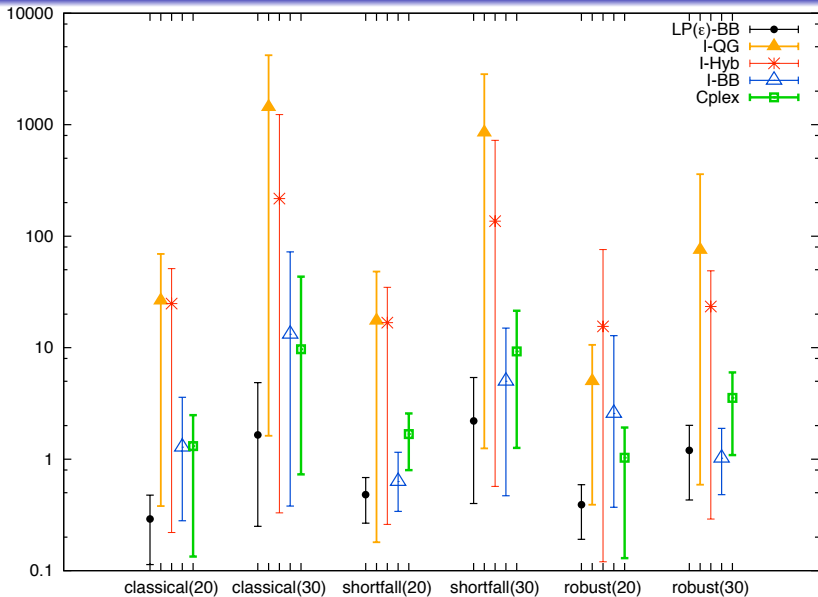
$(LB, \mathcal{H}) := \text{ProcessNode}(l^k, u^k, LB, \mathcal{H})$

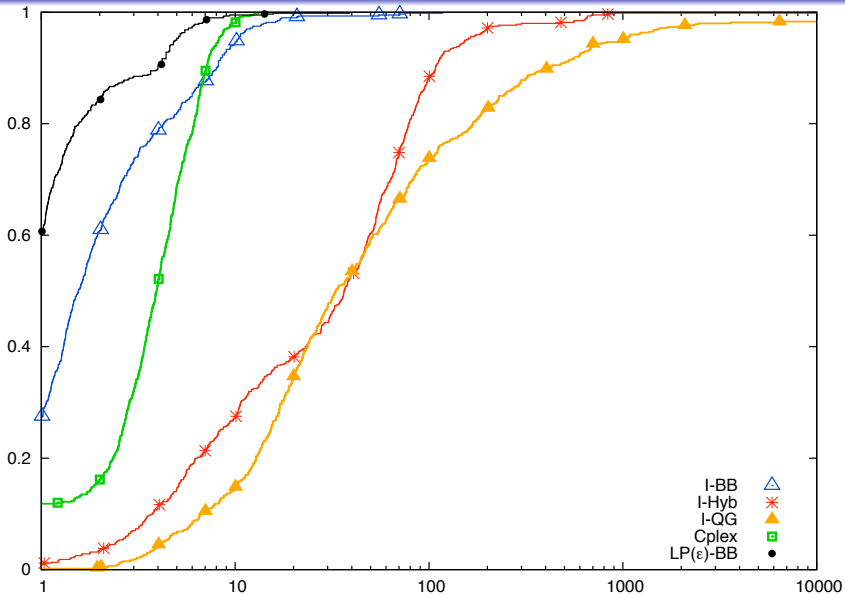
- 1 Solve  $\text{LP}(l^k, u^k)$  (Let  $(x^*, y^*)$  be the optimal solution).
- 2 **if**  $\text{LP}(l^k, u^k)$  *is feasible* **and**  $z_{\text{LP}(l^k, u^k)} > LB$  **then**
- 3     **if**  $x^* \in \mathbb{Z}^n$  **then**
- 4         Solve  $\text{NLP}(x^*)$ .
- 5         **if**  $\text{NLP}(x^*)$  *is feasible* **and**  $z_{\text{NLP}(x^*)} > LB$  **then**
- 6             Update  $LB$  to  $z_{\text{NLP}(x^*)}$ .
- 7         **end**
- 8         **Extra Steps**
- 9     **else**
- 10         Branch on  $x^*$  and add nodes to  $\mathcal{H}$ .
- 11     **end**
- 12 **end**

$(\text{LB}, \mathcal{H}) := \text{ProcessNode}(l^k, u^k, \text{LB}, \mathcal{H})$

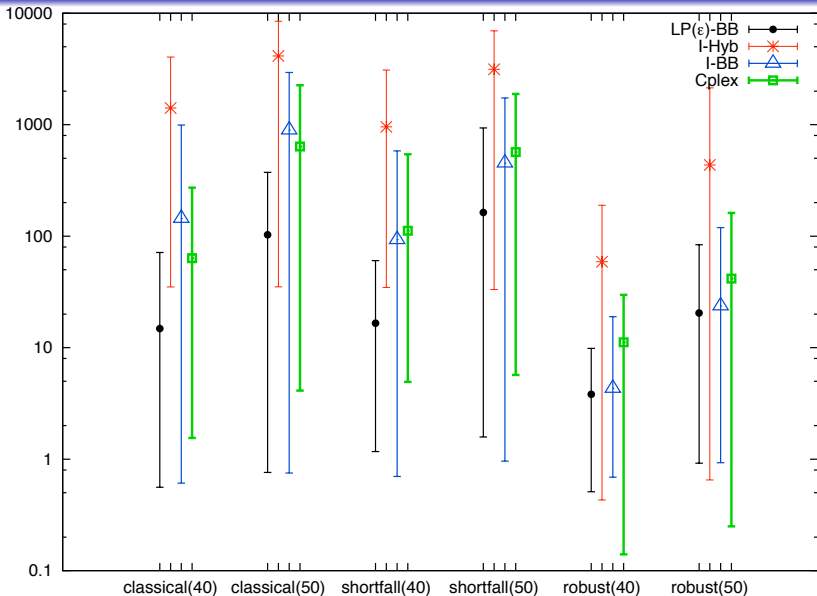
```
1 if  $l^k \neq u^k$  then
2   | Solve NLP( $l^k, u^k$ ) (Let  $(\tilde{x}, \tilde{y})$  be the optimal solution).
3   | if NLP( $l^k, u^k$ ) is feasible and  $z_{\text{NLP}(l^k, u^k)} > \text{LB}$  then
4     |   if  $\tilde{x} \in \mathbb{Z}^n$  then
5       |     | Update LB to  $z_{\text{NLP}(l^k, u^k)}$ .
6     |   else
7       |     | Branch on  $\tilde{x}$  and add nodes to  $\mathcal{H}$ .
8     |   end
9   | end
10 end
```

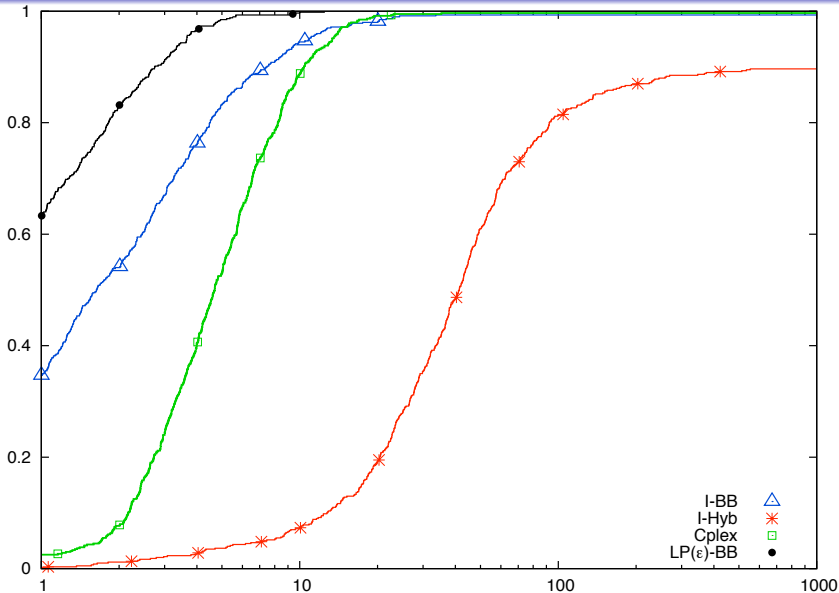
# Average Solve Times [s] for $n \in \{20, 30\}$



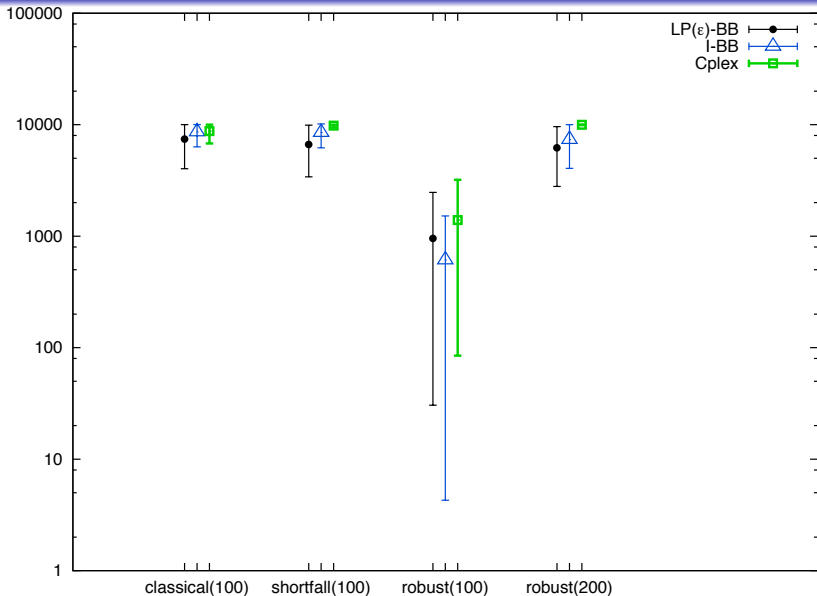
Performance Profile for  $n \in \{20, 30\}$ 

# Average Solve Times [s] for $n \in \{40, 50\}$



Performance Profile for  $n \in \{40, 50\}$ 

# Average Solve Times [s] for $n \in \{100, 200\}$



Performance Profile for  $n \in \{100, 200\}$ 